

CHIME Cal/Val Methodology & Status @ PDR

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Table of Content



CHIME Mission Overview

CHIME Status

CHIME Product Overview

Calibration Methodology

- On ground calibration
- CHIME Inflight calibration

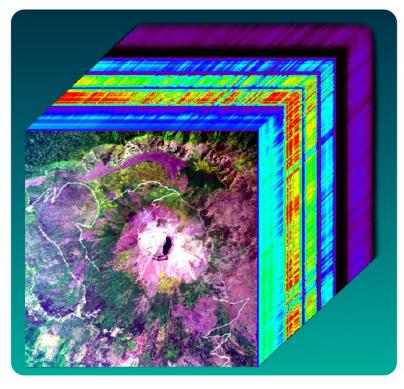
Dedicated Data Quality activities including:

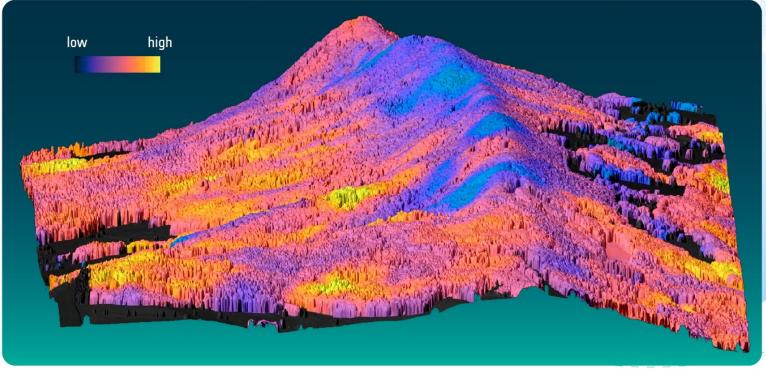
- HYPERNET
- CEM-PAL
- SRIX4Veg
- Cal/Val Park

CHIME Mission Objectives



- Provide routine hyperspectral measurements in support of EU- and related policies for the management of natural resources & assets
- Support food security, agriculture and raw materials, soil properties
- Secondary Applications: biodiversity and ecosystem sustainability, forestry management, environmental degradation, lake/coastal ecosystems and water quality, snow grain size/albedo, snow impurities)





Physiological diversity of a temperate forest (Airborne imaging spectroscopy APEX data - Schaepman, Jehle et al. 2015)

CHIME Key Requirements



Operational hyperspectral observations of land and coastal areas

Spectral range: 400 – 2500 nm

Spectral bandwidth and SSI ≤ 10nm

Ground Resolution: 30 m

Revisit 12.5 days (2 satellites)

High radiometric accuracy, low spectral/spatial mis-

registration

High SNR

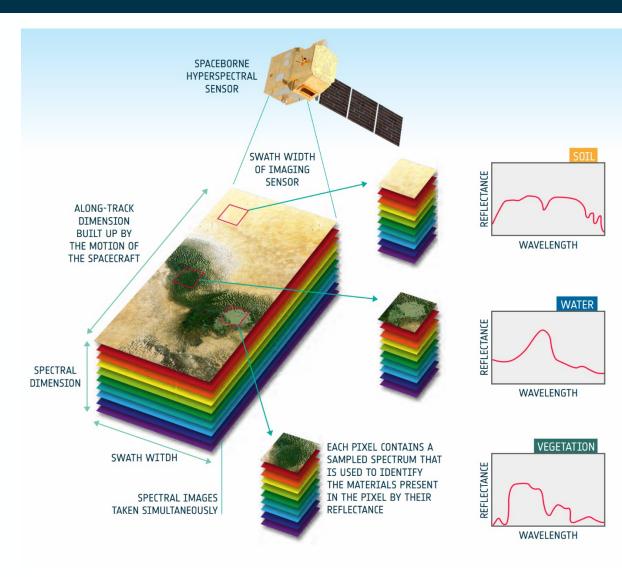
Matching performance of parallel missions (e.g. EnMAP, PRISMA, SBG)

Core data products:

L1-B Top-of-atmosphere (TOA) radiance

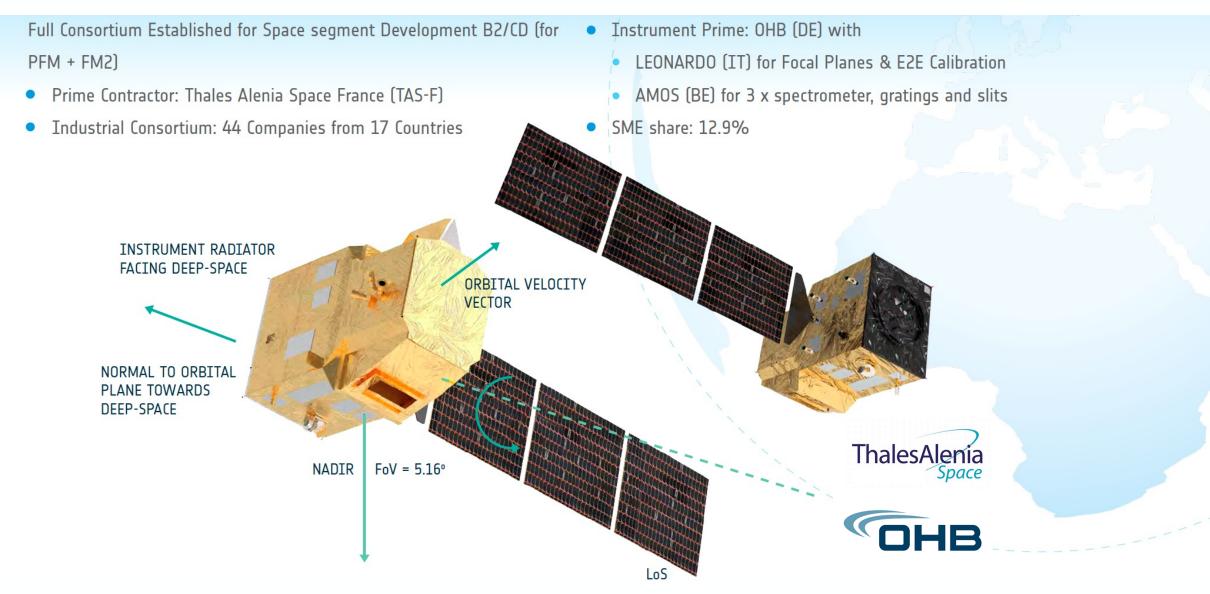
L1-C Ortho-rectified TOA reflectance

L2-A Ortho-rectified bottom-of-atmosphere (surface) reflectance



CHIME Space Segment

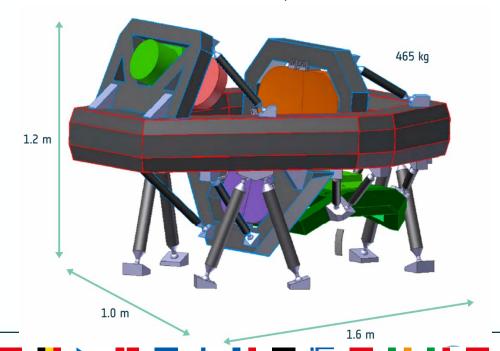


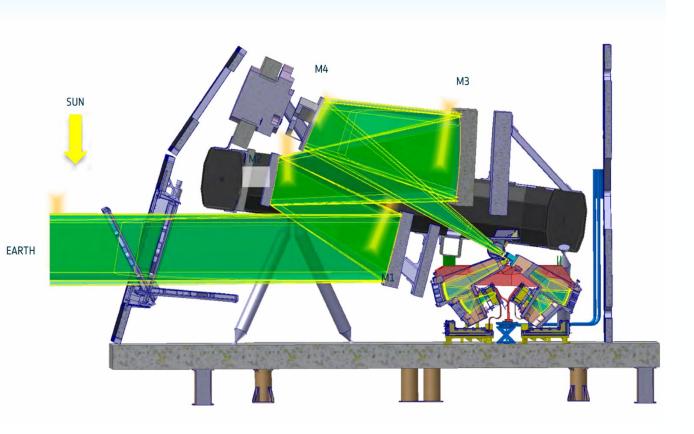


CHIME Programmatic Status



- System PDR Board held 15th July 2022
- Instrument HSI PDR started
- PDR Closeout expected in October 2022
- Start of Phase C/D expected in Q4 2022
- CDR expected Q2 2025
- QAR PFM: mid 2028, FAR FM2: mid 2029





Conceptual design for the optical accommodation of telescope and spectrometers for the staggered slit design

CHIME High Priority Prototype L2-B Products



DOMAIN	THEMATIC AREA	VARIABLES CHPPP	CHIME Candidate Algorithms			
	Assessment of biophysical and biochemical	Leaf/Canopy Pigment Content	Semi-empirical modelling based on narrow-band vegetation indices; Hybrid methods based on ANN/LUT or other machine learning algorithms applied to vegetation canopy radiative transfer models outputs (e.g. PROSAIL).			
		Leaf/Canopy Nitrogen Content				
	variables related	LAI	Narrow-band vegetation indices; Hybrid methods			
AGRICULTURE / FOOD SECURITY	to the crops and	Canopy Water Content	based on ANN/LUT or other machine learning algorithms e.g. GPR methods applied to vegetation canopy reflectance			
LOOD SECORTLY	of agronomic interest	Leaf/Canopy Pigment Content	models (e.g. PROSAIL).			
		Leaf Mass/Area				
	Topsoil	Soil organic carbon content	Chemometrics modelling (e.g. PLSR); Spectral analysis; Spectral indices;			
	properties	Soil texture (clay, silt, sand)	Machine learning (e.g. Random Forest)			
		Mineral identification / classification (Kaolinite, Smectite, Jarrosite, Dolomite)				
GEOLOGY & MINERALS	Raw material detection	Hematite – Goethite distribution	Sub-pixel linear unmixing Tetracorder type (EnGeoMap/PRISM)			
		Ferric oxide content				
		Kaolin Cristallinity				

CHIME High Priority Prototype Products



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FOOD SECORITY	or agronomic interest	Leaf/Canopy Pigment Content	models (e.g. PROSAIL).		
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CHIME Calibration Methodology



→ <u>Pre-launch calibration/characterisation</u> of key instrument performance (proper traceability, documentation)

→ Post-launch calibration

• In-flight calibration:

Allowing monitoring of performances, adjustment, modeling, etc.

Vicarious calibration:

- ✓ Equipped sites
- ✓ Pseudo invariant calibration sites (PICS)
- ✓ Rayleigh
- ✓ Deep Convective Clouds
- ✓ others

→ **Validation**

→ Data quality checks and characterisation

Overview Of CHIME Calibration Concepts (1/3)



CHIME SYSTEM CALIBRATION,
CHARACTERISATION
AND VALIDATION PLAN,
Thales Alenia Space

	Memo	Calibration	Method	Frequency and Operation duration estimation	Orbit part	Satellite slew	Acquisition mode	Data rate	Platform constraints
S	un Calib		Full Aperture Diffuser Equipment (FADE): Absolute radiometric reference by measurement of the on-board solar diffuser included in the FADE.	Once per week max	North pole	No	NOM	Binned (2x2)	none (TBC) Calibration mode
	Shutter Dark Calib	On-Board Dark Calibration	Internal Calibration Switching Unit (ICSU): Dark acquisition and offset calibration by blocking light path with the ICSU.	Twice per orbit	before and after observation	No	NOM	Binned (2x2)	none (TBC) Calibration mode
	Linear Calib	On-Board Linearity Calibration	Linear Calibration Source Unit (LCSU): Illuminate detector with LEDs in LCSU and perform integration time scan	Once per week	Eclipse	No	NOM	Binned (2x2)	none Calibration mode
:	Spectral Calib	On-Board Spectral Calibration	Spectral Calibration Source Unit (SCSU): measurement of absortion features from ion doped filter-glass illuminated with sun light via the FADE	Once per week Embedded in Sun Calib sequence	Eclipse	No	SPECCAL	Spectrally unbinned (2x1) 1 frame/3	none Calibration mode
	Sun Equal	•	Full Aperture Diffuser Equipment (FADE): Relative measurement on the on-board solar diffuser in FADE in order to derive the equalization gains for sub pixel	Twice per year	North pole	No	FULLRETINA	Unbinned 1 frame/5	none (TBC) Calibration mode
	Shutter Dark Equal	On-Board Dark Equalization	Internal Calibration Switching Unit (ICSU): Dark acquisition and offset for sub-pixel by blocking light path.	Twice per year	North pole	No	FULLRETINA	Unbinned 1 frame/5	none (TBC) Calibration mode
-	Desert Equal Calib		Vicarious: Radiometric field-of-view equalization by measurement of desert targets with a 90° yaw	Twice per year	Observation	Yaw	NOM	Binned (2x2)	guidance and Satellite pointing

Overview Of CHIME Calibration Concepts (2/3)



Memo	Calibration	Method	Frequency and Operation duration estimation	Orbit	Satellite slew	Acquisition mode	Data rate	Platform constraints
Geo bias (Vicarious: Scenes acquired on Regions of Interest at different latitudes Matching with references (GCPs or well- located images)	Routine verification - potential re-calibration 6 months (TBC) for seasonal effect	Observation	No (TBC)	NOM	Binned (2x2)	None (TBC) Instrument in pushbroom over observation areas
Lun Cal		Vicarious: Manoeuvre to point field centre to moon. Perform scan with 5 times spatial along track oversampling.	Twice per month	Eclipse	3 axis slew	NOM	Binned (2x2)	Pointing sequence around eclipse
De Spa Cal	ce Calibration	Vicarious: Acquire frames during lunar calibration manoeuvre while pointing to deep space.	Twice per month	Eclipse	3 axis slew	NOM	Binned (2x2)	Pointing sequence around eclipse
Da Oce Cal	an Dark	Vicarious: Dark scene and offset calibration by measurements during eclipse above dark ocean scene (e.g. in North or South pacific ocean)	Once per revisit	Eclipse	No	NOM	Binned (2x2)	None Instrument in push broom over observation zone

"CHIME SYSTEM CALIBRATION, CHARACTERISATION AND VALIDATION PLAN", Thales Alenia Space

Overview Of CHIME Calibration Concepts (3/3)



Memo	Calibration	Method	Frequency and Operation duration estimation	Orbit part	Satellite slew	Acquisition mode	Data rate	Platform constraints
Lunar Verif	MTF & Straylight verification	Vicarious: Manoeuvre to point field centre to moon. Perform scan with 5 times spatial along track oversampling.	Commissioning	Eclipse	3 axis slew	GEOCAL	Spatial Unbinned Spectral binned 1x4	Pointing sequence around eclipse
Desert Spectral verif	Desert Radiometric Equalization	Vicarious: Radiometric field-of-view equalization by measurement of desert targets with a 90° yaw for spectral verification purposes	Commissioning	Observation	Yaw	SPECAL	Spectrally unbinned (2x1) 1 frame/3	guidance and Satellite pointing
Geom static LOS Calib	each pixel of	Vicarious: Scenes acquired on Rol Matching with numerous GCPs spread all over the swath or dense correlation on reference images	Commissioning – Cal/Val Phase no re-calibration expected	Observation	No (TBC)	GEOCAL	Spatial Unbinned Spectral binned 1x4	None Calibration mode - Instrument in pushbroom over observation areas

CHIME calibration and verifications performed during commissioning

Data Quality activities for CHIME and other optical missions



ESA Validation Program

is composed by a set of different complementary activities bringing elements that need to be combined together.

Inter-comparison against tailored and precise Fiducial Reference Measurements (FRM): few points but precise

Inter-comparison against in-situ measurements: more points less precise

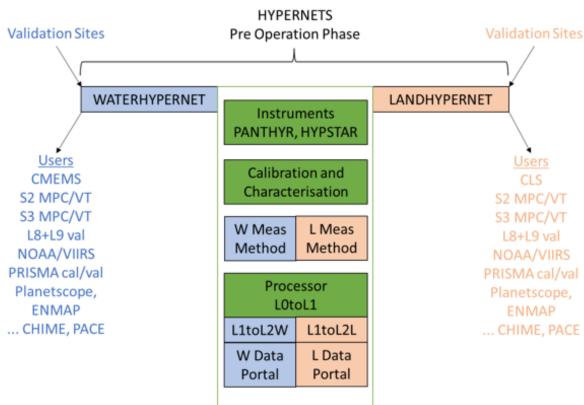
validation against others sources: inter-satellite comparison

validation using **monitoring tools**: statistics, trend, systematic quality control, etc.

validation using **Level 3** data: statistical comparison between various Level 3 from various sensors for a cross-validation of the products

Next Generation Hyperspectral Radiometric Validation Networks for Water and Land Surface Reflectance - the HYPERNET project – PI Kevin Ruddick (RBINS)





Overview of synergies and differences between water reflectance and land surface reflectance activities with common activities (green), water-specific activities (blue) and land-specific activities (beige).

- for land, measuring upwelling radiance from multiple nadir and azimuth angle to build up information on the Hemispheric-Directional Reflectance Function (HDRF) (Schaepman-Strub et al. 2006; Kuester et al. 2014); and
- (both water and land), scanning the skydome to check for clouds and/or obstructions or to estimate aerosol properties.





(PANTHYR radiometer System and HYPSTAR® radiometer system. Cable tie spikes are used for bird avoidance.

Next Generation Hyperspectral Radiometric Validation Networks for Water and Land Surface Reflectance - the HYPERNETS project – PI Kevin Ruddick (RBINS)



Based on the success of the AERONET-OC federated network for multispectral measurement of water reflectance, the HYPERNETS concept is to operate a:

- Hyperspectral radiometer(s) with both radiance and irradiance heads, on a Pan-and-tilt pointing system, with
- A control system comprised of computer, electronics and auxiliary sensors, power supply and communications (e.g. Ethernet/2G/3G/4G) ensuring data acquisition and transmission, deployed over an
- International network of autonomous sites, acquiring data following a
- Standardised measurement method, and transmitting data for
- Standardised data processing and web portal data distribution, backed up by SI traceable laboratory calibration and characterisation of radiometers, and Full estimation of measurement uncertainties. according to Fiducial Reference Measurement (FRM) principles.

While this approach clearly follows closely the AERONET-OC organisation (G. Zibordi et al. 2009) the following differences are noted (in addition to the obvious multispectral/hyperspectral difference):

- Two types of hyperspectral radiometer (and associated pan-tilt and control systems) are accepted in the network: TRIOS/RAMSES radiometer (a mature, high performance COTS radiometer available since 2000 with radiance and irradiance variants) or the HYPSTAR® radiometer (a prototype twin-head new radiance/irradiance radiometer currently being tested within H2020/HYPERNETS to be commercialised from 2023).
- Land surface reflectance is measured in addition to water reflectance





HYPERNET Validation Sites – Growing Number of Sites







Validation Test sites

LAND and WATER validation network



(c) HYPERNETS Consortium, 2021 (RBINS, TARTU, SU, CNR, NPL, GFZ, CONICET)

- Growing Number of Sites
- Multi Missions

Satellite/Instrum	Agency	Launch date	Spectral
ent		4 1 0015	coverage
Sentinel-2/MSI	ESA (Companions)	A: Jun 2015	442-2202 nm
	(Copernicus)	B: Mar 2017	Multispectral
		C: 2024?	
Sentinel-3/OLCI	EUMETSAT/ESA	D: ? A: Feb 2016	400-1020 nm
Sentinei-3/OLCI	(Copernicus)	B: Apr 2018	Multispectral
	(Copernicus)	C: 2024?	Mullispectial
		D: ?	
PRISMA	ASI (Italy)	Mar 2019	400-2500 nm
111011111	/ tor (italy)	Mai 2010	Hyperspectral
ENMAP	DLR (Germany)	Apr 2022	420 to 2450 nm
	, ,,	'	Hyperspectral
Landsat-8/OLI	NASA/USGS	Feb 2013	423-2300 nm
			Multispectral
			(+thermal
			infrared)
Landsat-9/OLI	NASA/USGS	Sep 2021	423-2300 nm
			Multispectral
			(+thermal
) (UDO	N10 A A	0.10044	infrared)
VIIRS	NOAA	Oct 2011	402-2275 nm Multispectral
			•
			(+thermal
Doves	Planetlabs	2015 + many	infrared) 430-885 nm
Superdoves	i iaiietiabs	2010 · Illally	Multispectral
Skysats			Manapoonar
Pléiades	CNES/EADS	1A: Dec 2011	450-915 nm
		1B: Dec 2012	Multispectral
		Neo3-6: Apr	·
		2021+	
CHRIS-PROBA	ESA	Oct 2001	400-1050 nm
MTG (geo)	EUMETSAT	I1: Nov 2022 ?	400-2200 nm
		12/13/14: ?	Multispectral
			(+thermal
OLUME	F04	0000	infrared)
CHIME PACE	ESA NASA	2028	Hyperspectral
SBG	NASA	?	Hyperspectral Hyperspectral
GLIMR (geo)	NASA	?	Hyperspectral
Newspace	Various	?	Multispectral/
Newspace	v anous		Hyperspectral?
Many others	Various	?	Various
	7 41.10 410		3 4.10 4.0

































CEM-PAL



The purpose of the Expansion Mission Product Algorithm Laboratory (or CEM-PAL) is to provide an environment for efficient prototyping of algorithms used to generate Expansion Missions Level 2 products, including algorithm modification, hosted processing, qualification functionalities and scientific validation environment.

The prototypes/processors/libraries/specific tools/validation data will be provided by external entities (i.e. specific contract for Product Algorithm Definition for each mission).

The ultimate goal is to allow the efficient development of extensions to the processing capabilities of the mission, especially the definition of improved or new core products and their migration to the ground segment

PAL = central role for the data quality activities - cal/val, processing algorithms improvements

SRIX4Veg – Surface Reflectance Inter-comparison eXercise for Vegetation



SRIX4Veg is an ESA-funded joint effort to ensure consensus on a Surface Validation Protocol using UAV-mounted hyperspectral Reflectance imagers.



It has been endorsed by CEOS and is conducted in the framework of the ESA FRM4Veg project.

Objectives:

- Testing user-based differences in surface reflectance UAV-based measurements (including instrument and operator biases as well as measurement collection procedures);
- Helping design field measurement protocols that are clear and can be easily applied by all users;
- Ensuring international buy-in and consensus on the field measurement protocols for global SR validation.























Project partners:









SRIX4Veg – Surface Reflectance Inter-comparison eXercise for Vegetation

eesa





Pictures from the SRIX4Veg field campaign last July

CAL/VAL Park Concept



- ✓ Dedicated to VHR and HR optical missions;
- ✓ Open to both multi-spectral and hyperspectral missions;
- ✓ For both **TOA radiance and reflectance** and **BOA reflectance**;
- ✓ Open to be used by both the "institutional space" and the "commercial/new space";
- ✓ Common "playground" to test and run **new cal/val methodologies, instruments, and initiatives**;
- ✓ Open to include temporary and long-term instrumentation and initiatives;
- ✓ **Scalable** (as far as possible) to accommodate new needs and new types of EO missions that may come in the next years;
- ✓ Building on already existing cal/val technologies AND new technologies and methods;
- ✓ Able to support the ever growing European and international EO industrial ecosystem;
- ✓ Multi-Agency joint effort;
- ✓ Synergetic approach not to duplicate efforts (and budgets).

- The "Cal/Val Park" concept is under definition phase.
- Discussions are on-going for a joint ESA-ASI effort (interest from other space agencies and institutions to be investigated).

Conclusion



- ✓ CHIME development is progressing well
- ✓ First Cal/Val plan proposed by TAS/OHB and currently under review (part of PDR)
- ✓ Additional Cal/Val activities and concepts are under development
- ✓ The ESA Cal/Val plan (incl. phase E2) will be established for CDR