

Preliminary Evaluation of the Mirror-Based Empirical Line Method using FLARE system (Surface Reflectance – Landsat Level 2)

SDSU Image Processing Laboratory

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CEOS – IVOS 34



August 29 2022

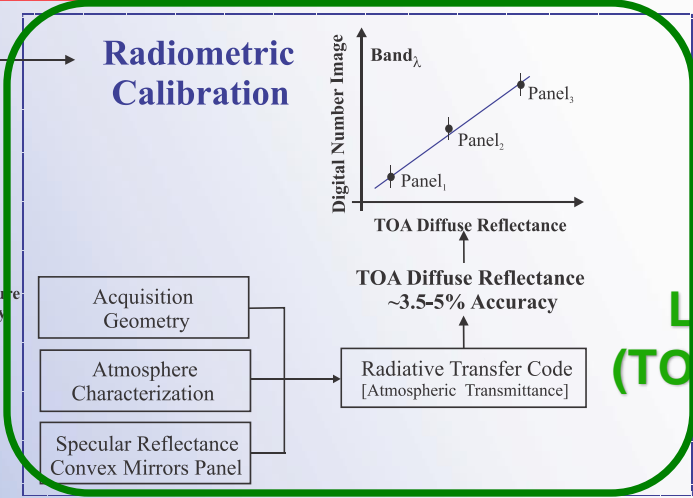
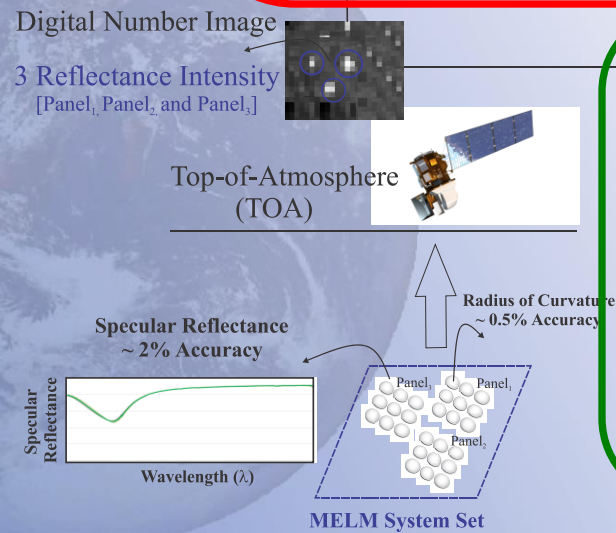
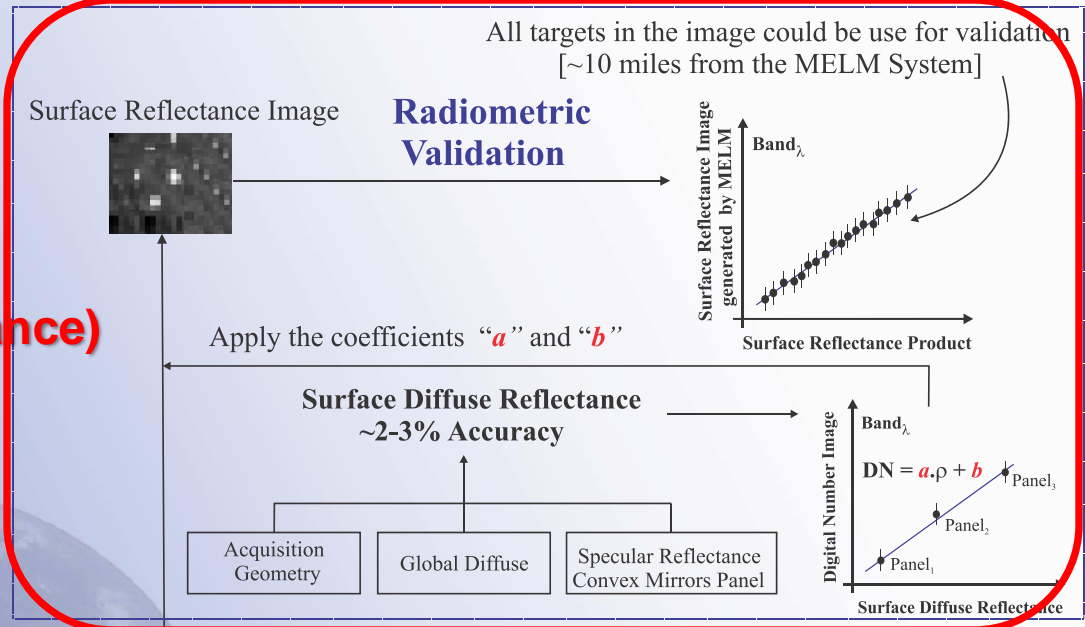
Outline

- ✓ **Introduction**
- ✓ **Mirror Empirical Line Method;**
- ✓ **FLARE** [Field, Line-of-sight Automated Radiance Exposure];
- ✓ **FLARE Radiometry;**
- ✓ **Lambertian (Diffuse) Equivalent Reflectance Factor;**
- ✓ **2020 & 2021 Data Acquisition ;**
- ✓ **Preliminary Results for Landsat;**
- ✓ **Final Considerations;**

Introduction

Mirror-based Empirical Line Method

**Level-2 Data
(Surface Reflectance)**



**Level-1 Data
(TOA Reflectance)**

Mirror-based Empirical Line Method

Empirical Line Method



- ✓ The MELM measures reference targets of known reflectance in the scene;
- ✓ The known reflectance targets are **convex mirrors**;
- ✓ If at least **two ground targets** with a known reflectance at different intensity levels are positioned within a scene, calibration/validation can be performed;
- ✓ The result from the regression calculation is the **gain** and **offset** coefficients that can be applied to all surfaces located in the scene [the assumption of a stable atmosphere within a minimum radius], providing **surface reflectance** retrieval image;
- ✓ This is the one of the key advantages of the MELM method: **making the larger region surrounding the convex mirror system location into an extended validation target**;

Mirror-based Empirical Line Method

FLARE Alpha deployed at Arlington's Farm (July 2020)



FLARE Alpha test platform long term loan agreement/partnership with **Labsphere**;



Mirror-based Empirical Line Method

Radiometry – Extended surface

TOA Intensity (Sensor Independent)

$$I(\lambda, \theta_r)_{TOA} = \frac{1}{4} \rho(\lambda, \theta_r) \tau_{\downarrow}(\lambda) \tau_{\uparrow}(\lambda) E_o(\lambda) R^2$$

[Watts/(sr micron)/mirror]

Effective At-Sensor Radiance (sensor and collection geometry specific)

$$L_{at-sensor}(\lambda, \theta_r) = \rho(\lambda, \theta_r) \tau_{\downarrow}(\lambda) \tau_{\uparrow}(\lambda) E_o(\lambda) \frac{R^2}{4GSD(x)GSD(y)}$$

[Watts/(m² sr micron)/mirror]

$\rho(\lambda, \theta_r)$ = Mirror specular reflectance at the reflectance angle θ_r ;

$\tau_{\downarrow}(\lambda)$ = Sun to ground transmittance;

$\tau_{\uparrow}(\lambda)$ = Ground to sensor transmittance;

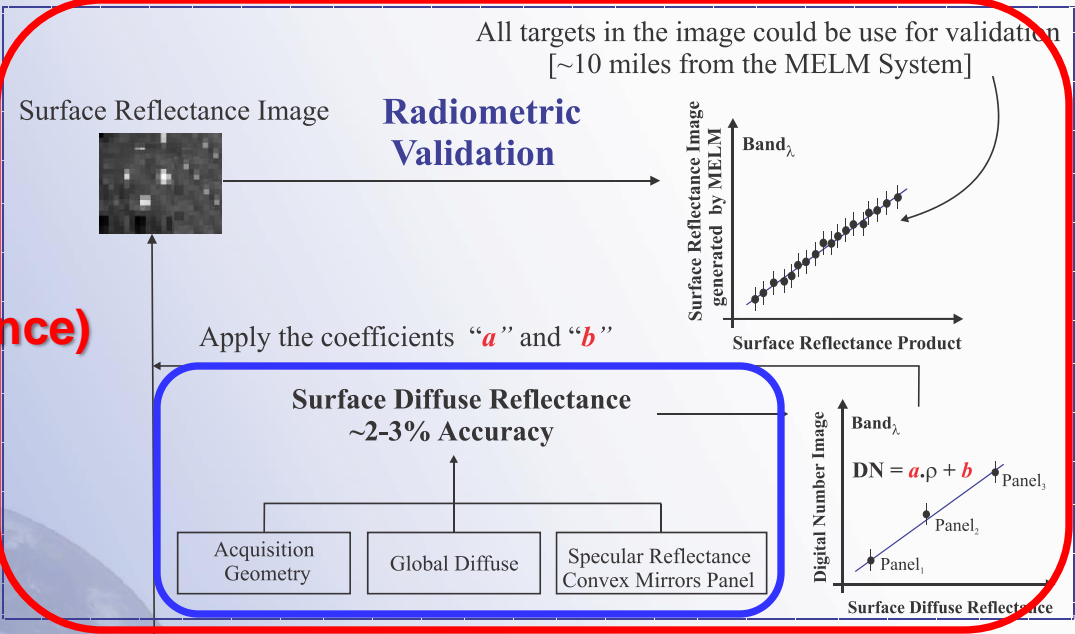
$E_o(\lambda)$ = Solar spectral constant;

R = Mirror radius of curvature (m);

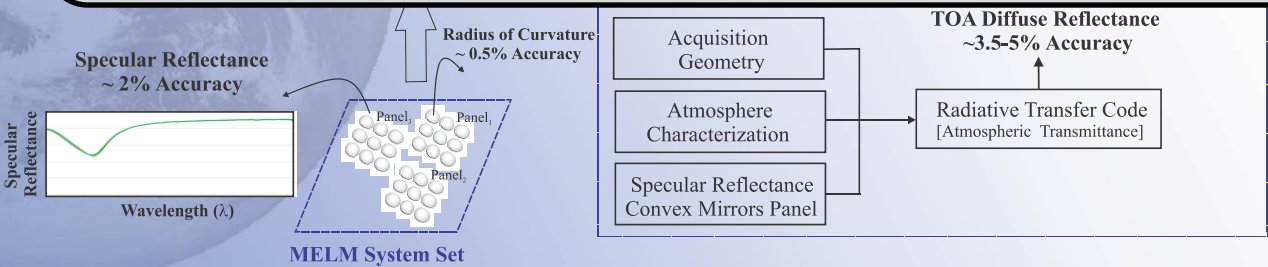
GSD = Ground sample distance (m);

Mirror-based Empirical Line Method

Level-2 Data
(Surface Reflectance)



In order to use a convex mirror as a ground reference target, however, the specular reflectance of the mirror must be converted to a **diffuse (Lambertian) reflectance**.



Mirror-based Empirical Line Method

August 23, 2020

Lambertian (Diffuse) Equivalent Reflectance Factor

$$\rho_F^{mir}(\lambda) = \left[\frac{1}{\cos\theta_o} + \left(f - \frac{1}{\cos\theta_o} \right) G(\lambda) \right] \frac{N\pi R^2}{4GSD_x GSD_y} \rho_m(\lambda)$$

$\rho(\lambda, \theta_r)$ = Mirror specular reflectance at the reflectance angle θ_r

θ_o = Solar zenith angle

f = Fraction of the hemispherical sky reflected by the mirror dome of half angular width θ_m .

$G(\lambda)$ = Diffuse to global ratio measured at the mirror target location

N = Number of mirrors

R = Mirror radius of curvature (m)

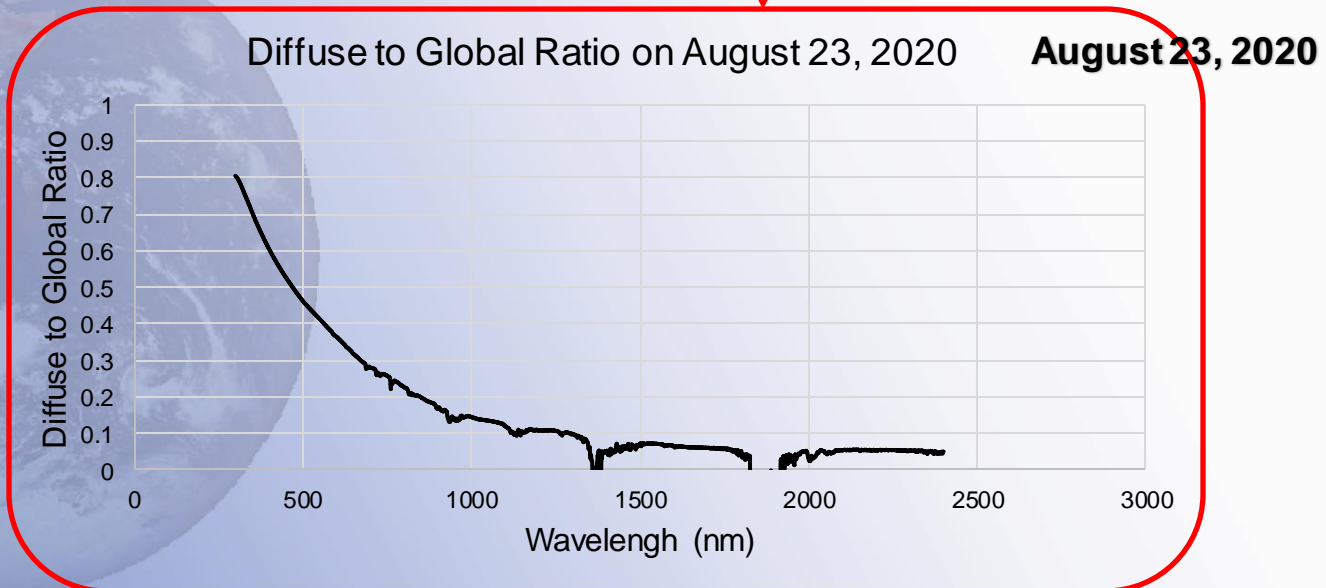
GSD = Line-of-site ground sample distance (m)

Mirror-based Empirical Line Method

August 23, 2020

Lambertian (Diffuse) Equivalent Reflectance Factor

$$\rho_F^{mir}(\lambda) = \left[\frac{1}{\cos\theta_o} + \left(f - \frac{1}{\cos\theta_o} \right) G(\lambda) \right] \frac{N\pi R^2}{4GSD_x GSD_y} \rho_m(\lambda)$$

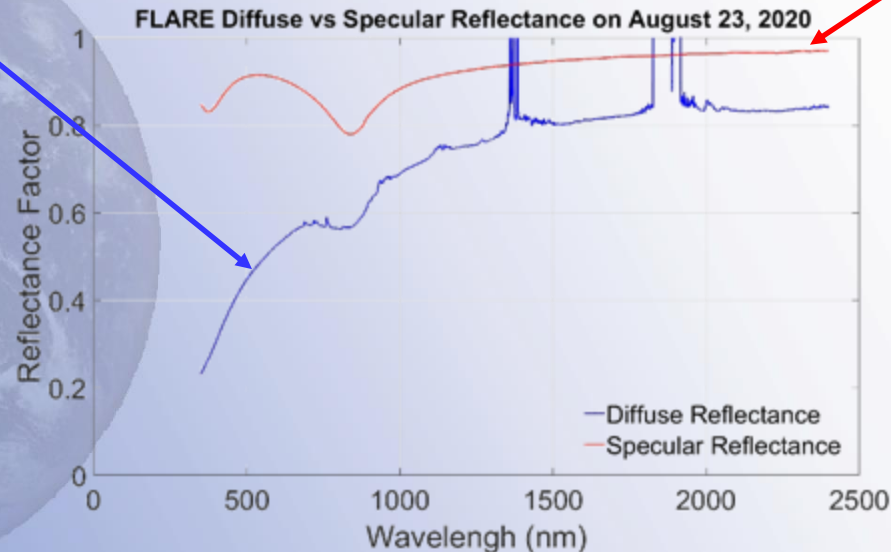


Mirror-based Empirical Line Method

August 23, 2020

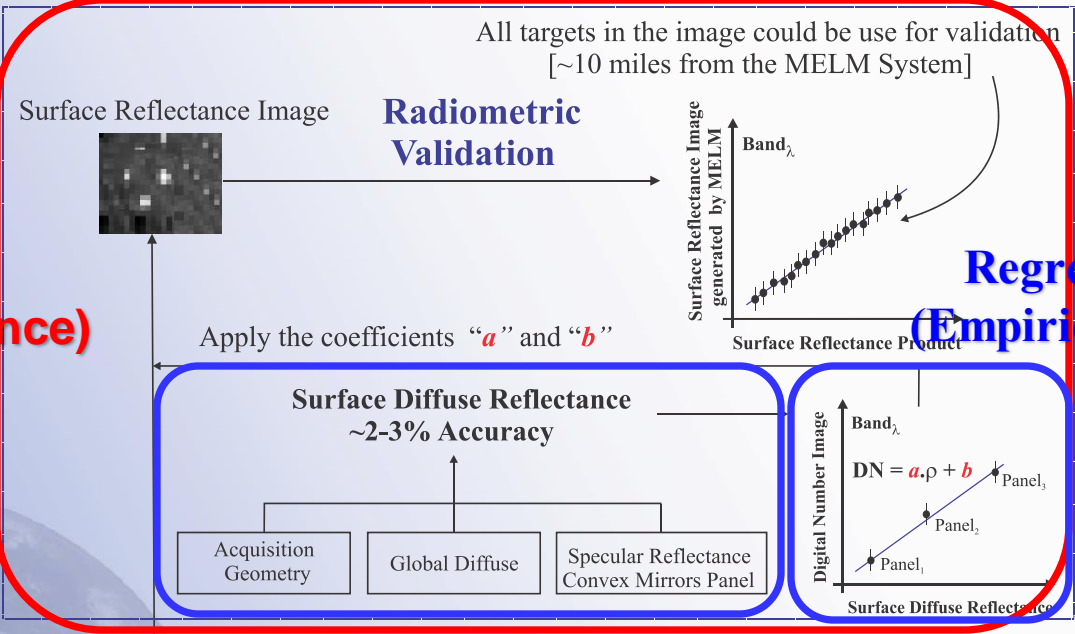
Lambertian (Diffuse) Equivalent Reflectance Factor

$$\rho_F^{mir}(\lambda) = \left[\frac{1}{\cos\theta_o} + \left(f - \frac{1}{\cos\theta_o} \right) G(\lambda) \right] \frac{N\pi R^2}{4GSD_x GSD_y} \rho_m(\lambda)$$

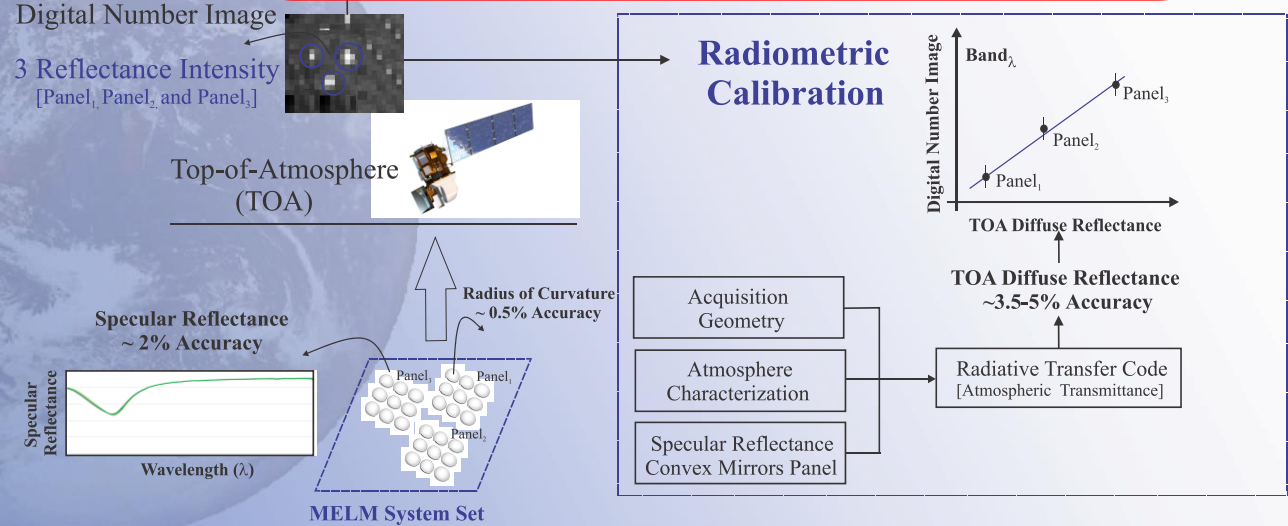


Mirror-based Empirical Line Method

**Level-2 Data
(Surface Reflectance)**

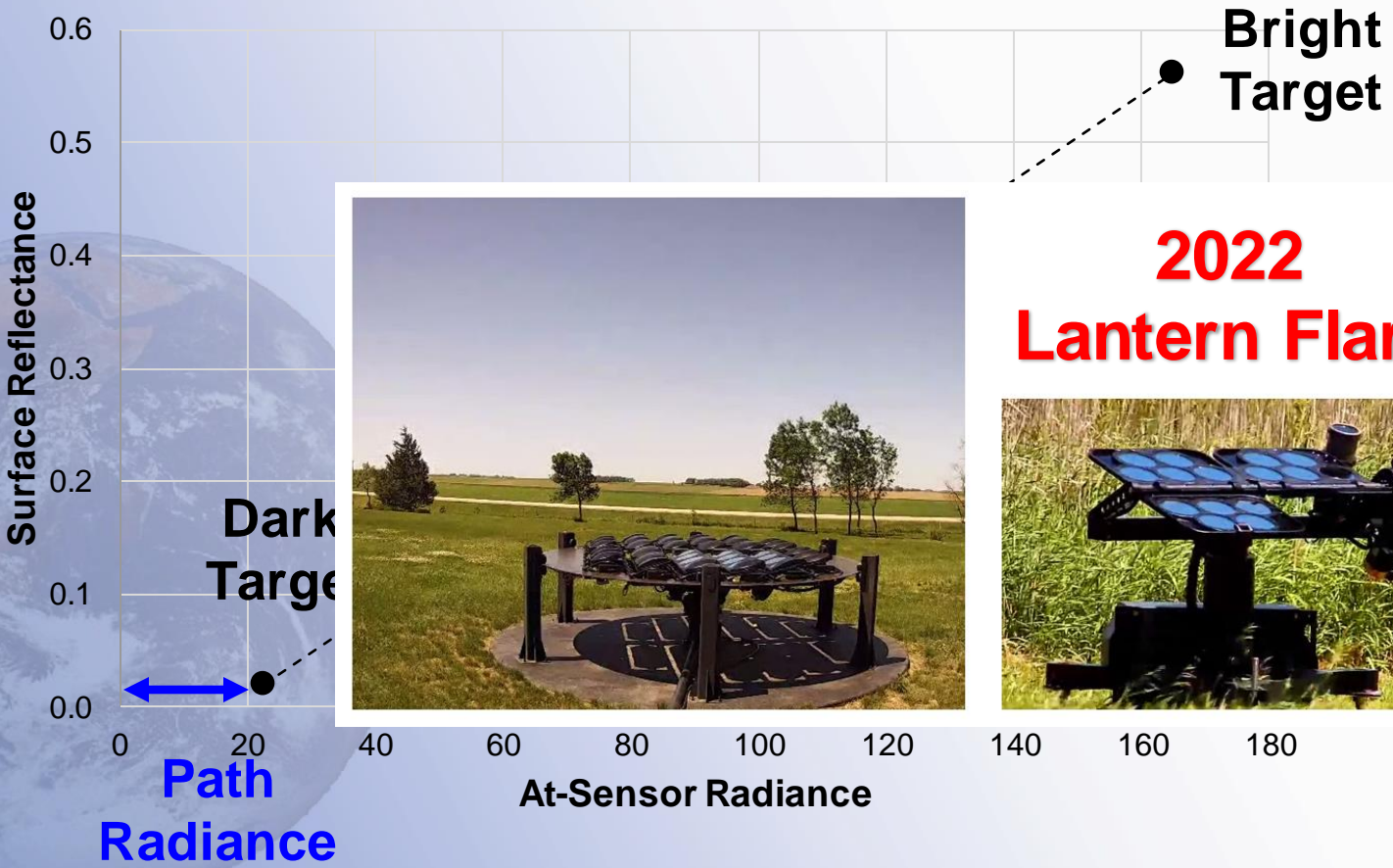


**Regression Analysis
(Empirical Line Method)**



Mirror-based Empirical Line Method

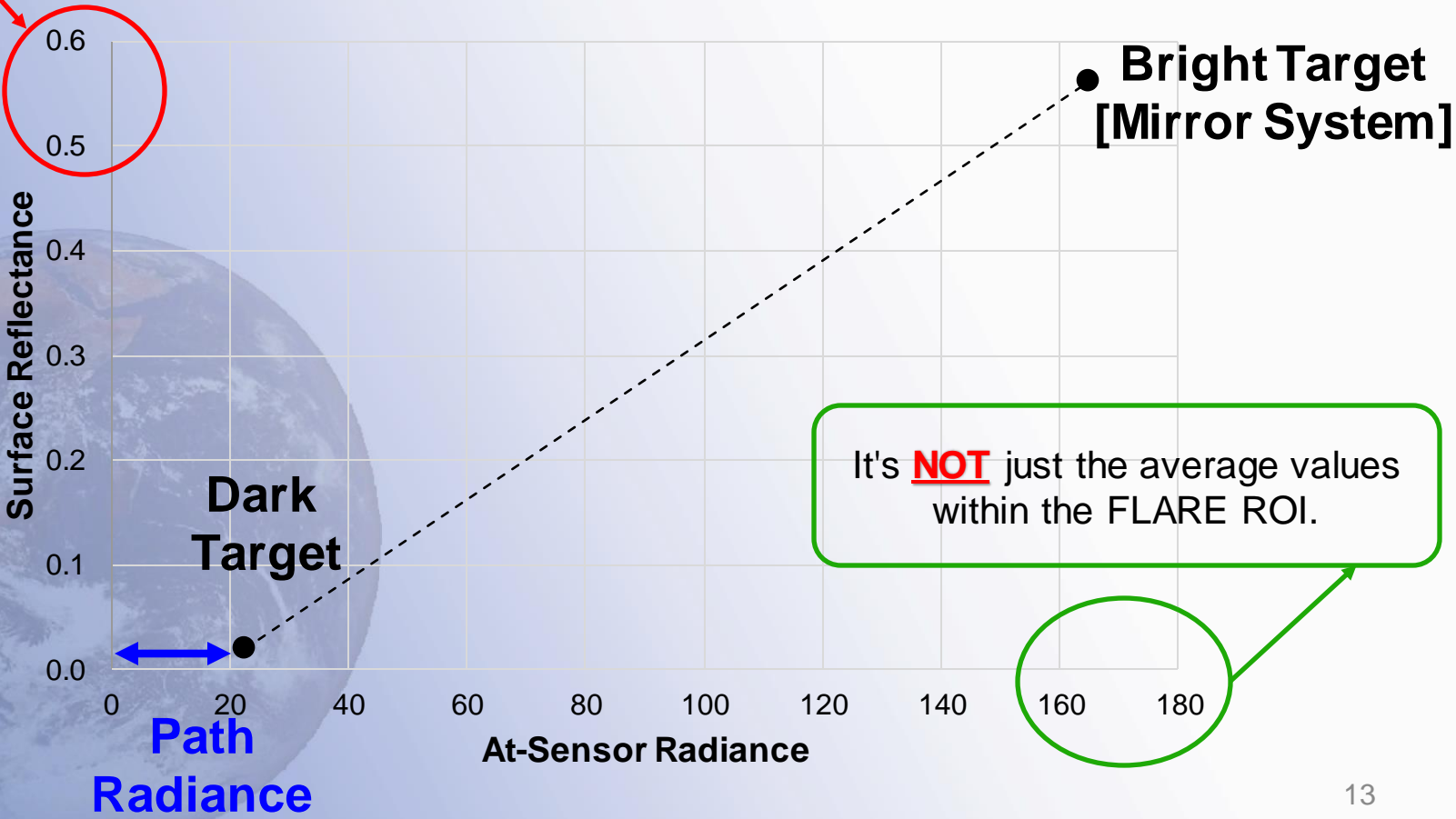
- ✓ Ideally, we would have more than one mirror system in the same scene - for a more robust regression ;
- ✓ 2020 and 2021 → **one FLARE system** - which provides the **bright target**;
- ✓ In some days we have the **ground measurement** (vegetation/soil) with the ASD - which provides the **dark target**;



Mirror-based Empirical Line Method

Diffuse Equivalent Reflectance Factor

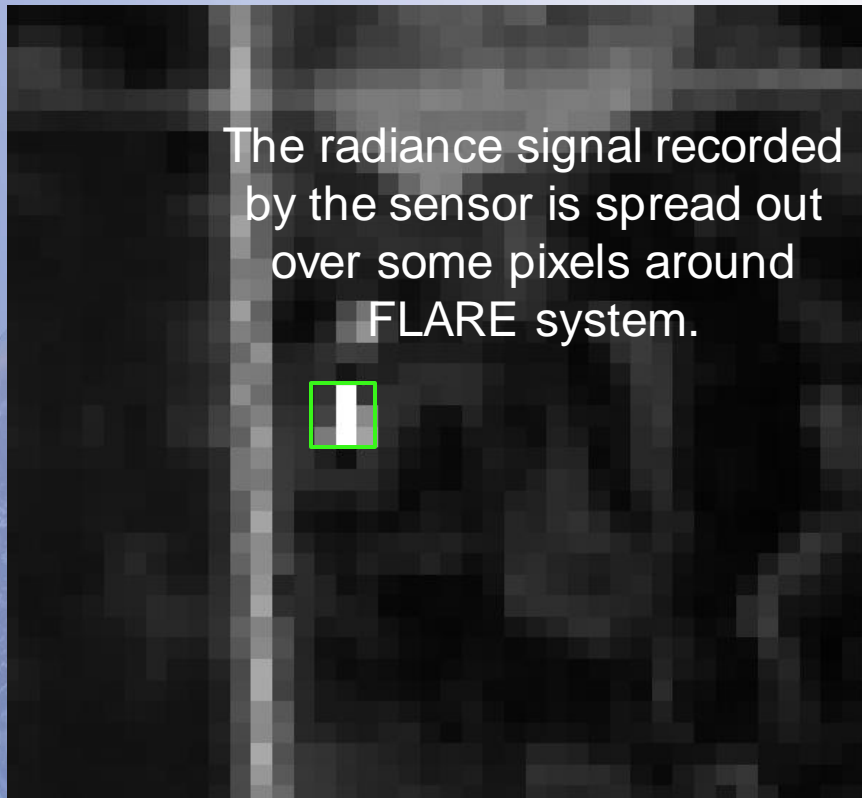
$$\rho_F^{mir}(\lambda) = \left[\frac{1}{\cos\theta_o} + \left(f - \frac{1}{\cos\theta_o} \right) G(\lambda) \right] \frac{N\pi R^2}{4GSD_x GSD_y} \rho_m(\lambda)$$



Mirror-based Empirical Line Method

August 23, 2020

FLARE At-Sensor Radiance measured from image:



The radiance signal recorded by the sensor is spread out over some pixels around FLARE system.

Landsat-8 OLI

Assuming the FLARE system signal impacts 9 pixels:

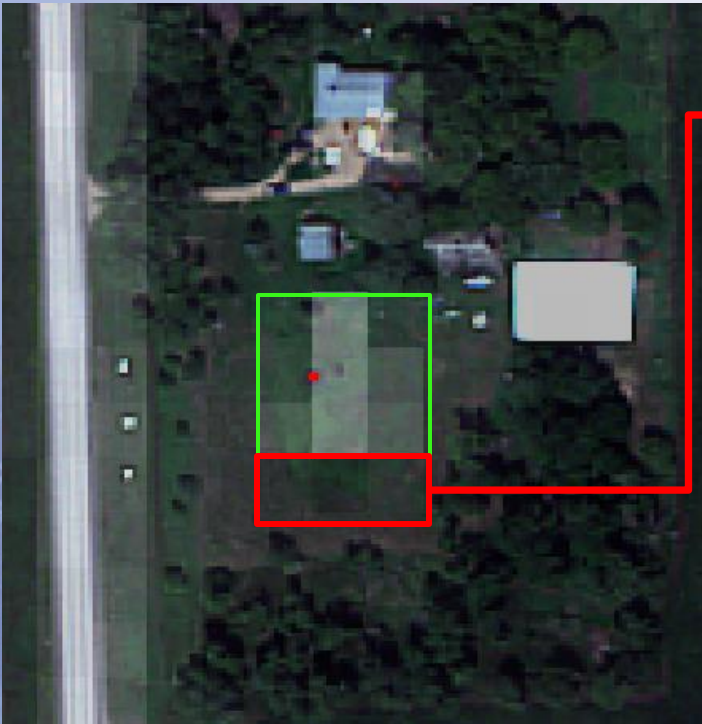
$$L_{Image} = \sum L_{Integrated_Response} = \sum_{n=1}^9 (L_n - \overline{L_{background}})$$

The critical key step is to remove the **background signal** and, consequently, leave only the signal coming from the FLARE/mirrors.

Mirror-based Empirical Line Method

August 23, 2020

Background Signal:



Background: Image Derived

Assumptions:

- (a) these **3 pixels** are not affected by the FLARE system; and
- (b) these **3 pixels** represent the same type of land cover* contained in the 9 pixels impacted by the FLARE system;

$$\overline{L}_{background} = \frac{\sum_{n=1}^3 L_n}{3}$$

$$L_{Image} = \sum L_{Integrated_Response} = \sum_{n=1}^9 (L_n - \overline{L}_{background})$$

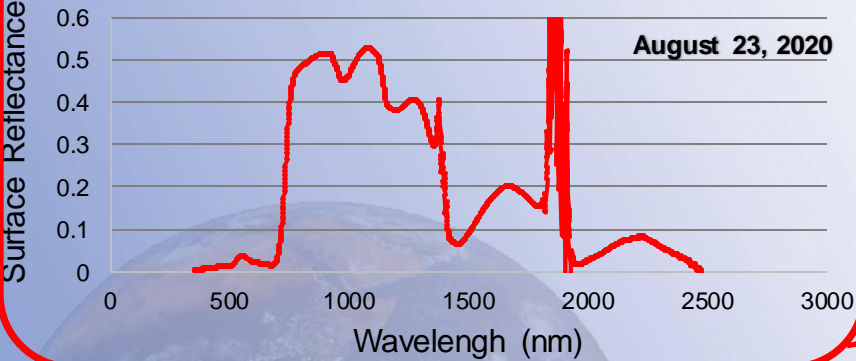
*Here the land cover is a mix of vegetation and soil.

Mirror-based Empirical Line Method

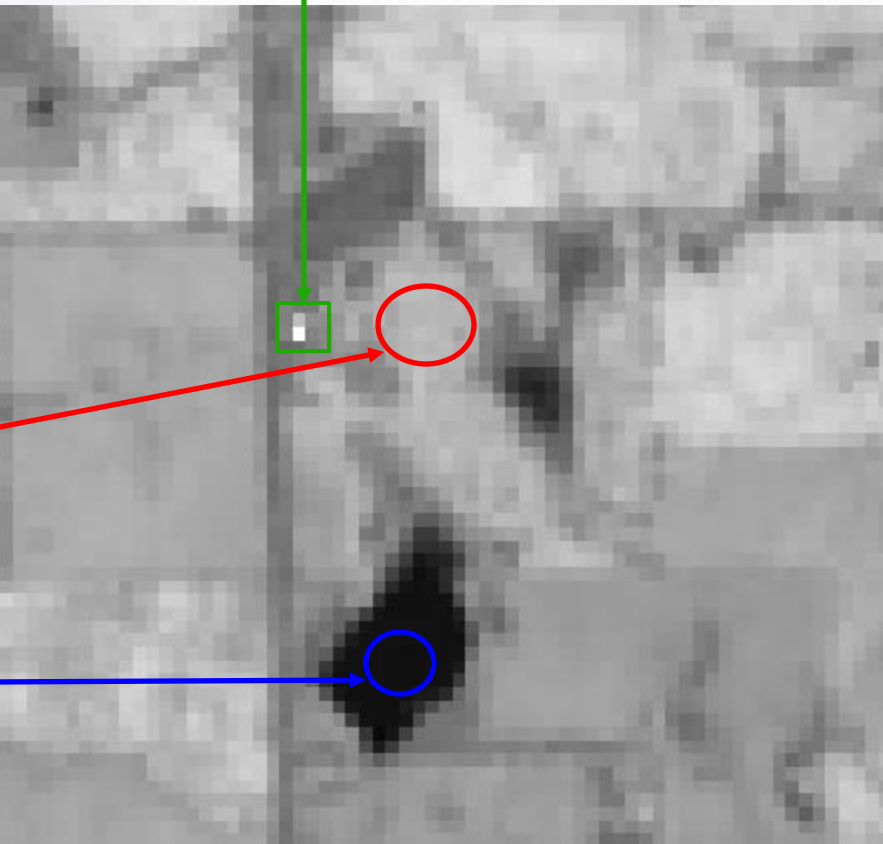
FLARE At-Sensor Radiance measured from image:

Soybean

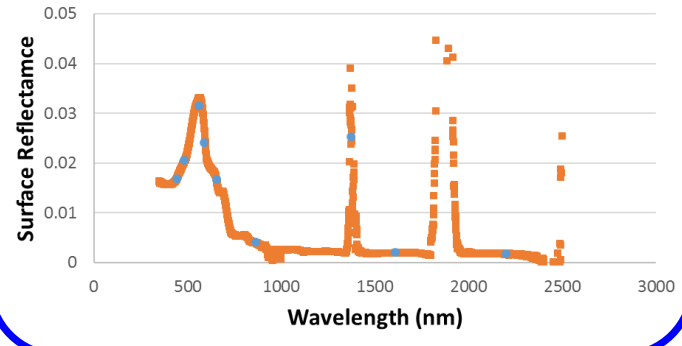
Surface Reflectance Soybean



FLARE



Water Collection ASD - Dakota Nature Park



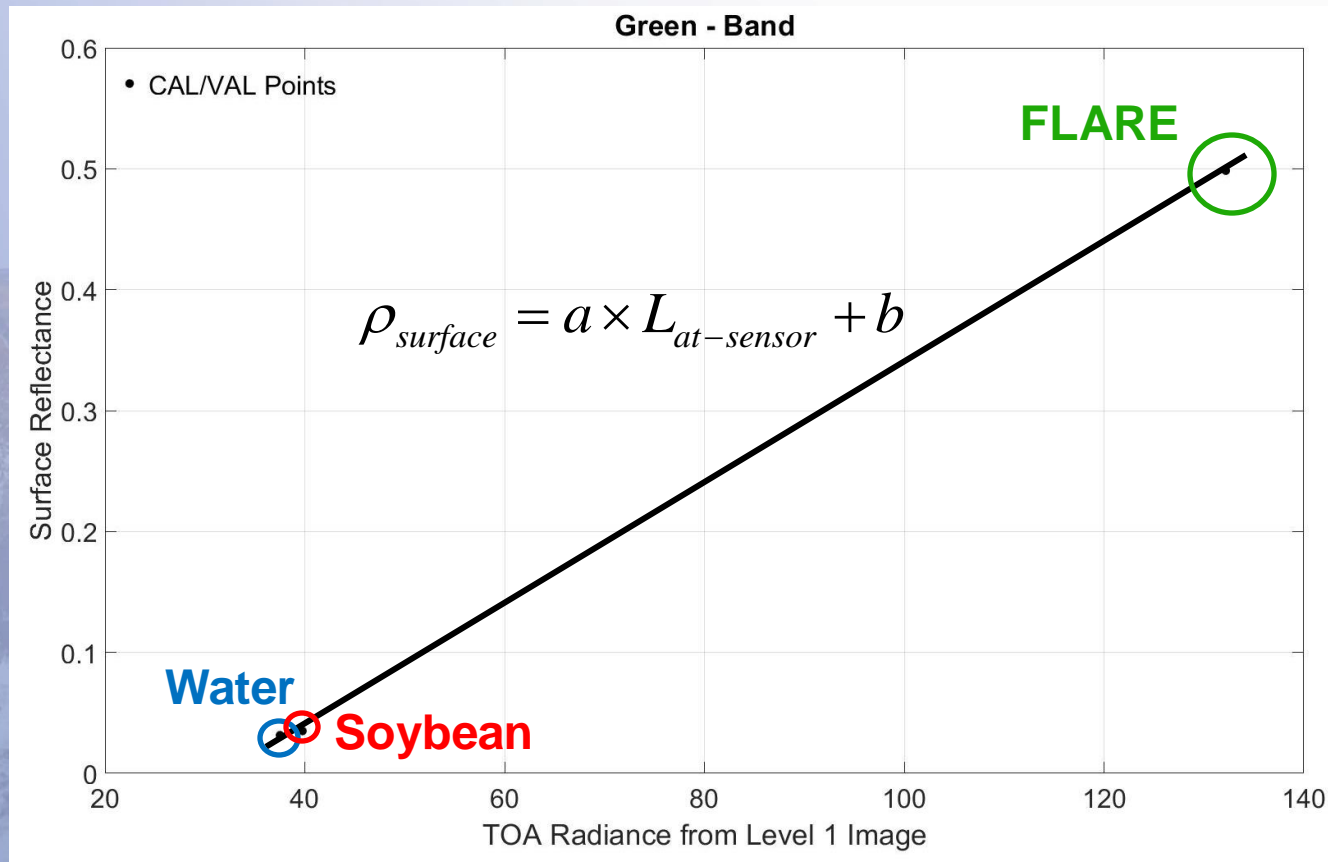
Water

Mirror-based Empirical Line Method

Preliminary Results

Green Landsat-8

August 23, 2020

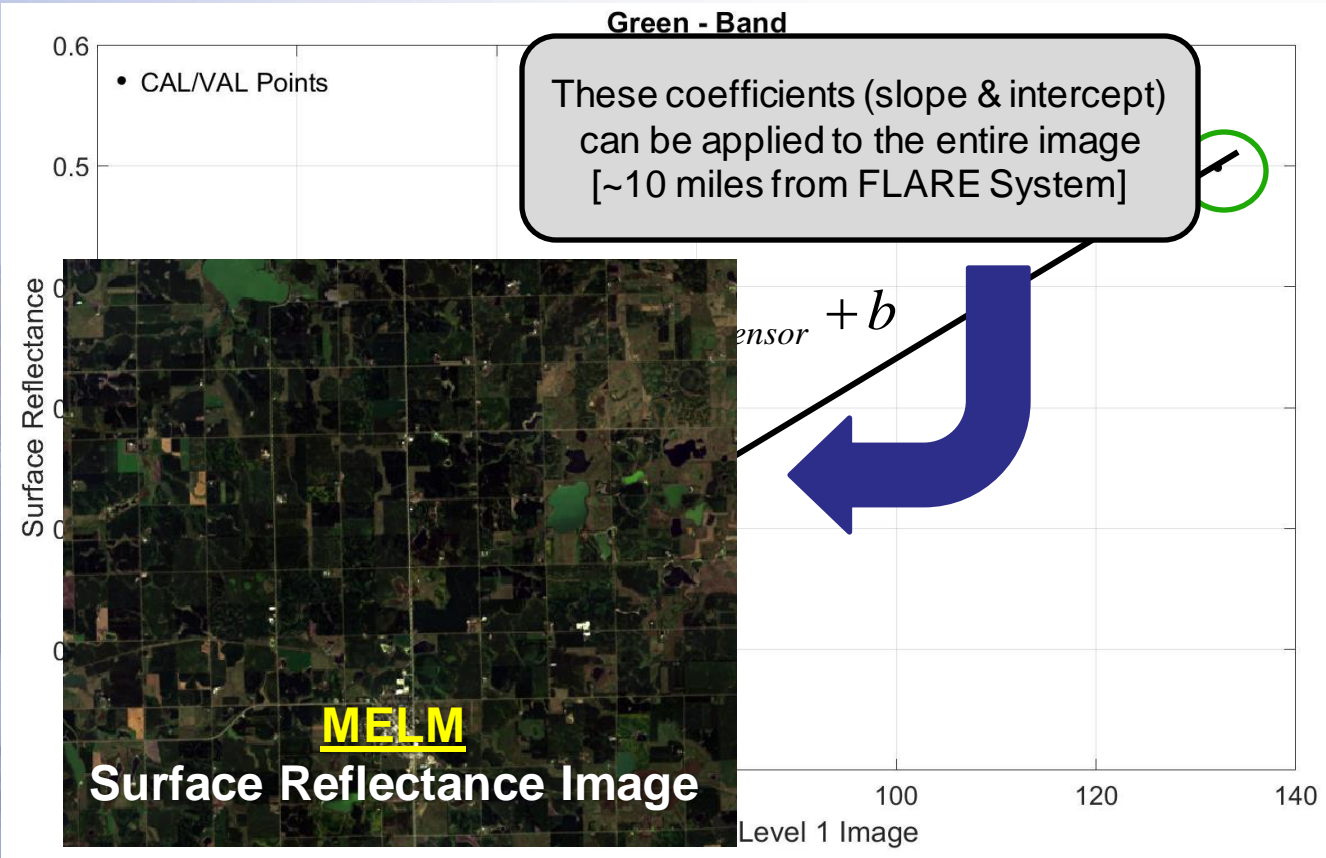


Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020

Green Landsat-8



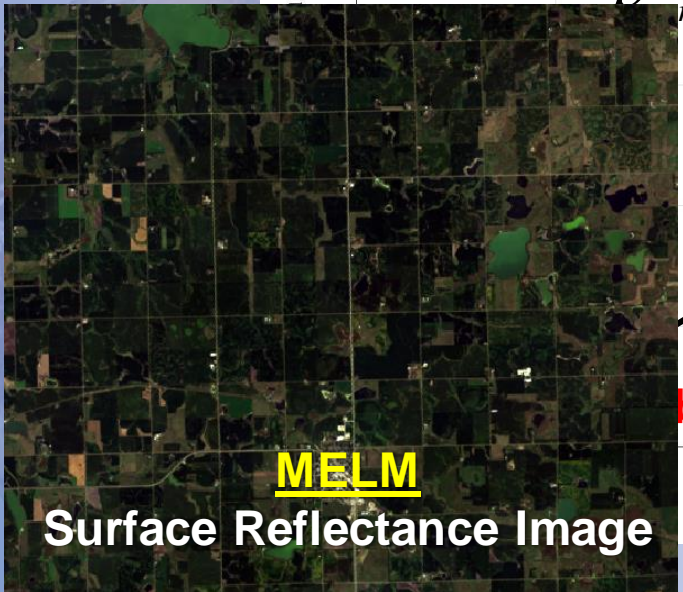
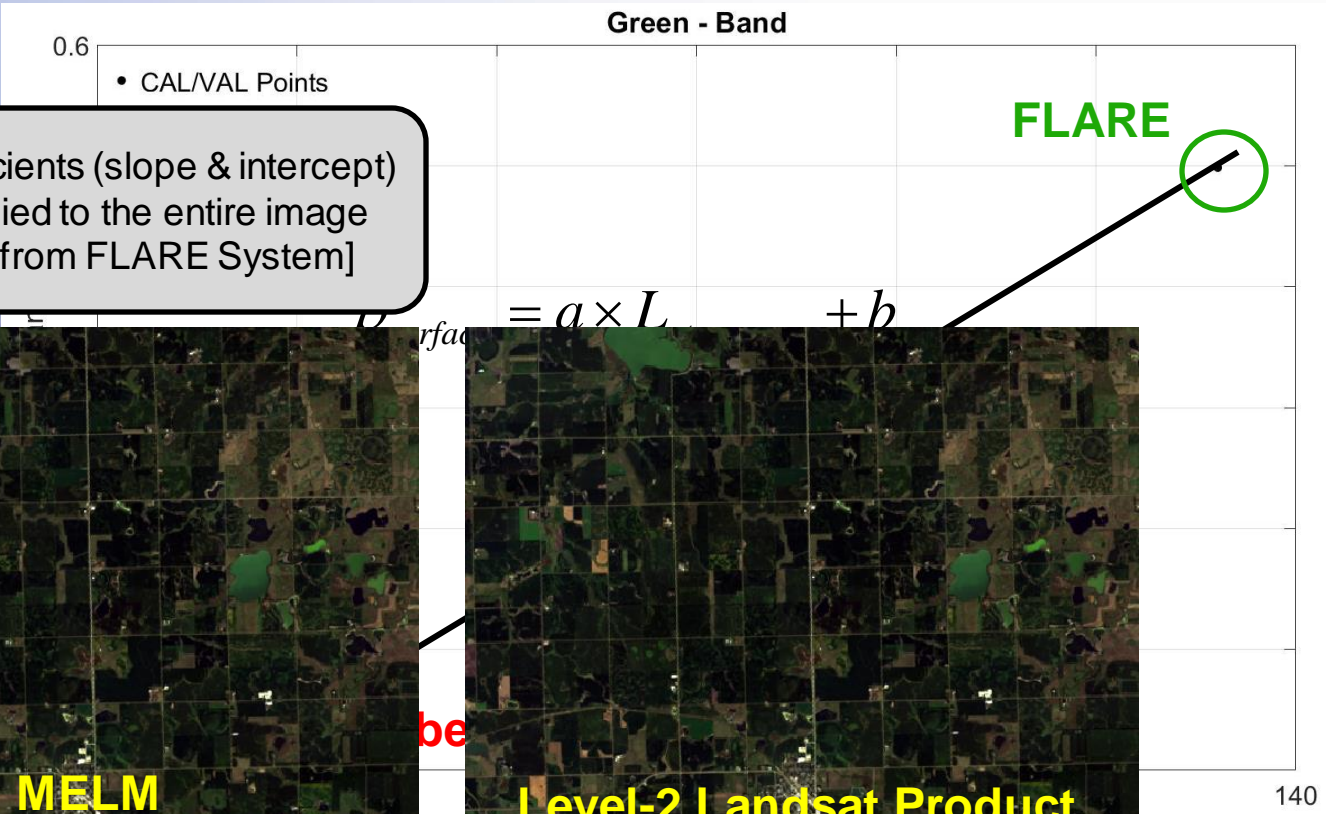
Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020

Green Landsat-8

These coefficients (slope & intercept) can be applied to the entire image [~10 miles from FLARE System]

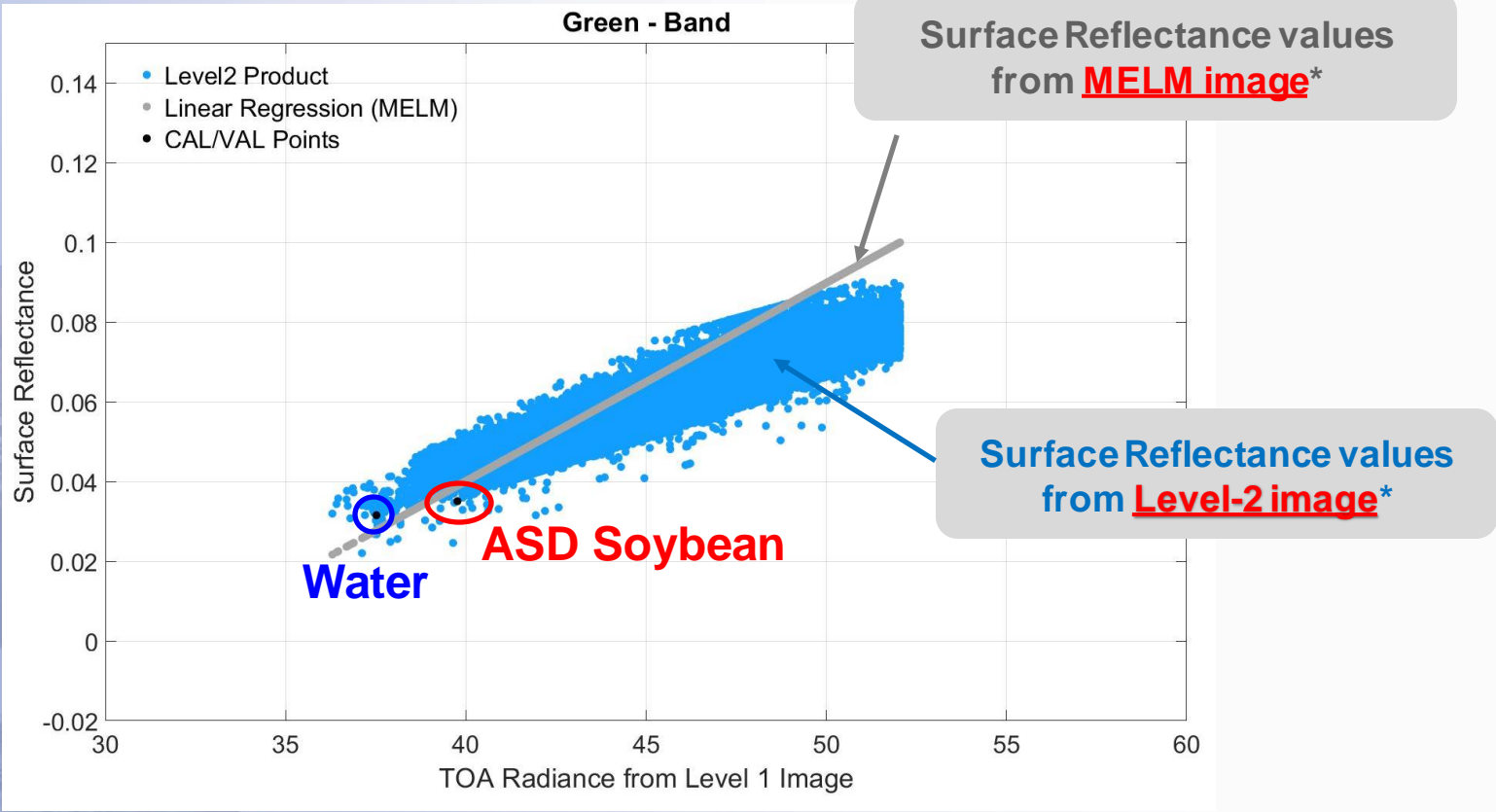


Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020

Green Landsat-8



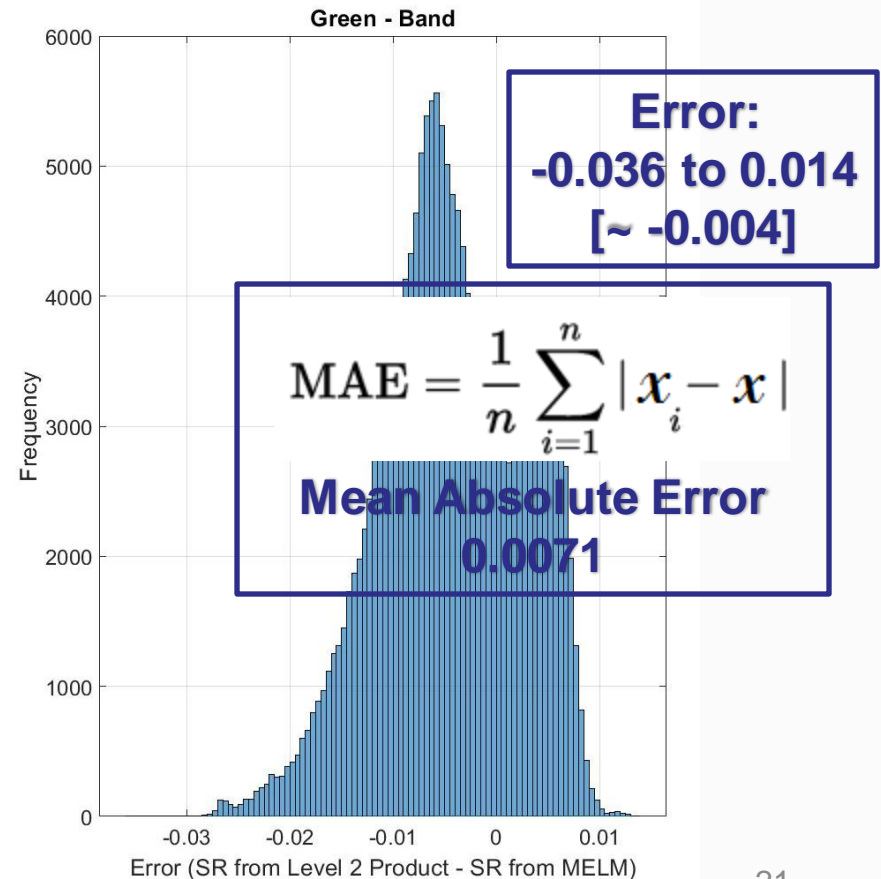
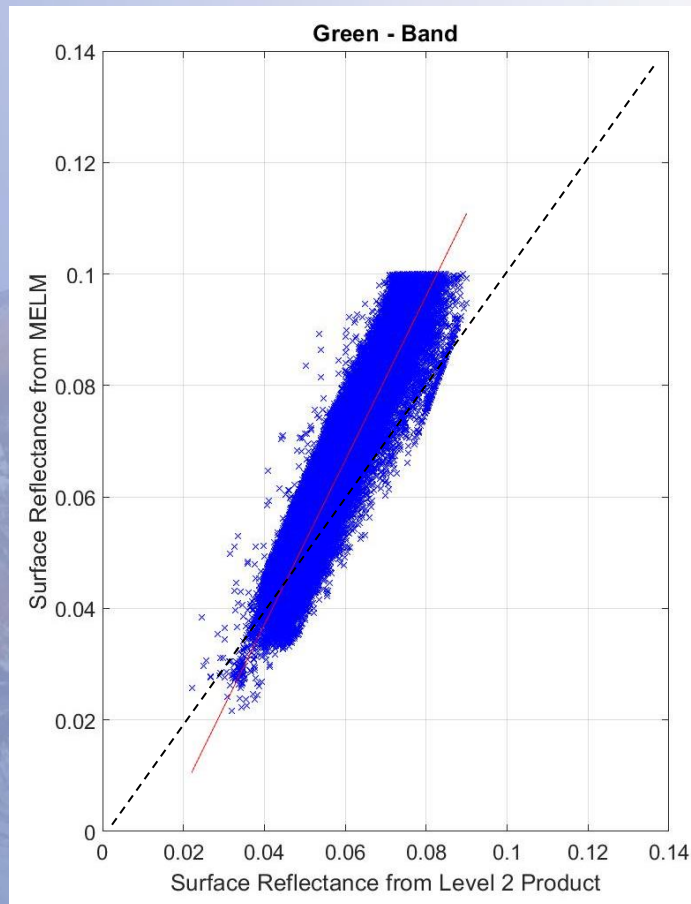
*[~10 miles from FLARE System]

Mirror-based Empirical Line Method

Preliminary Results

Green Landsat-8

August 23, 2020

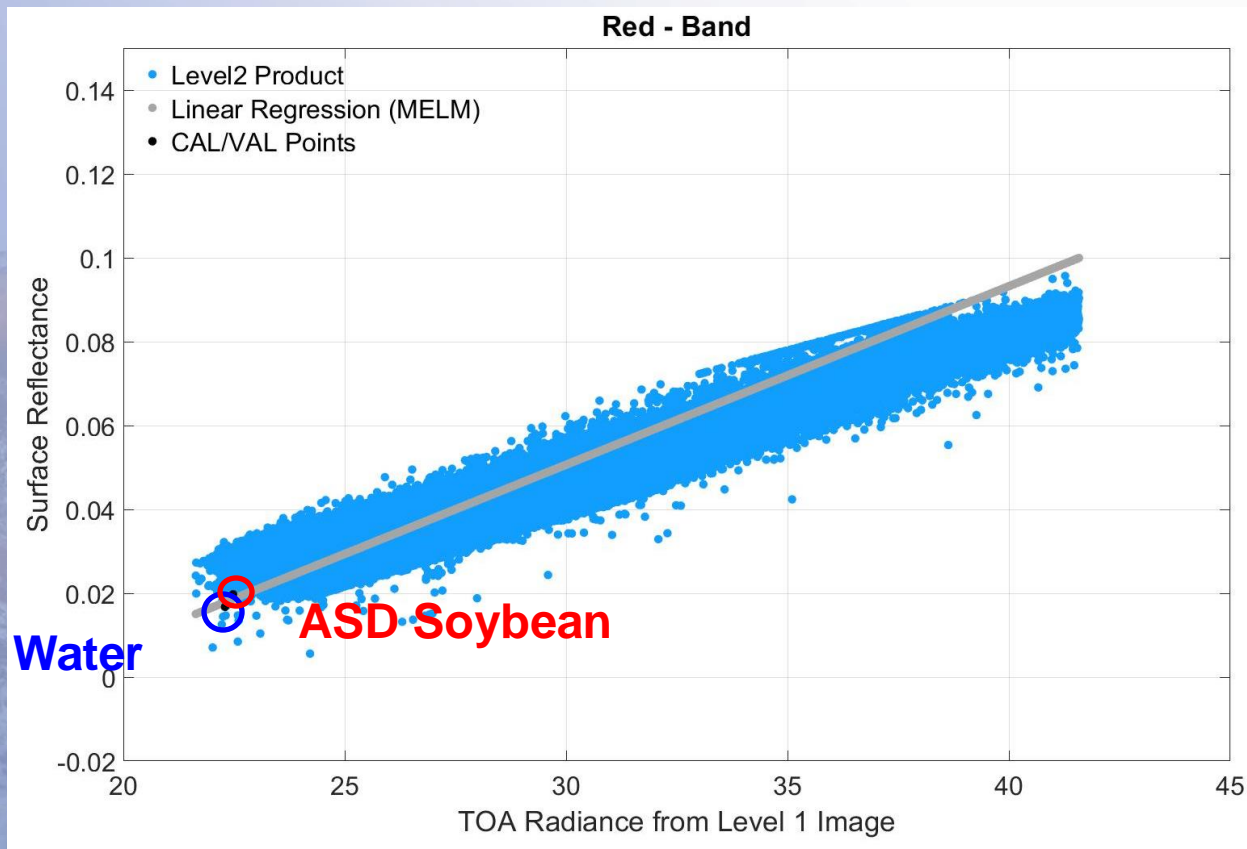


Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020

Red Landsat-8

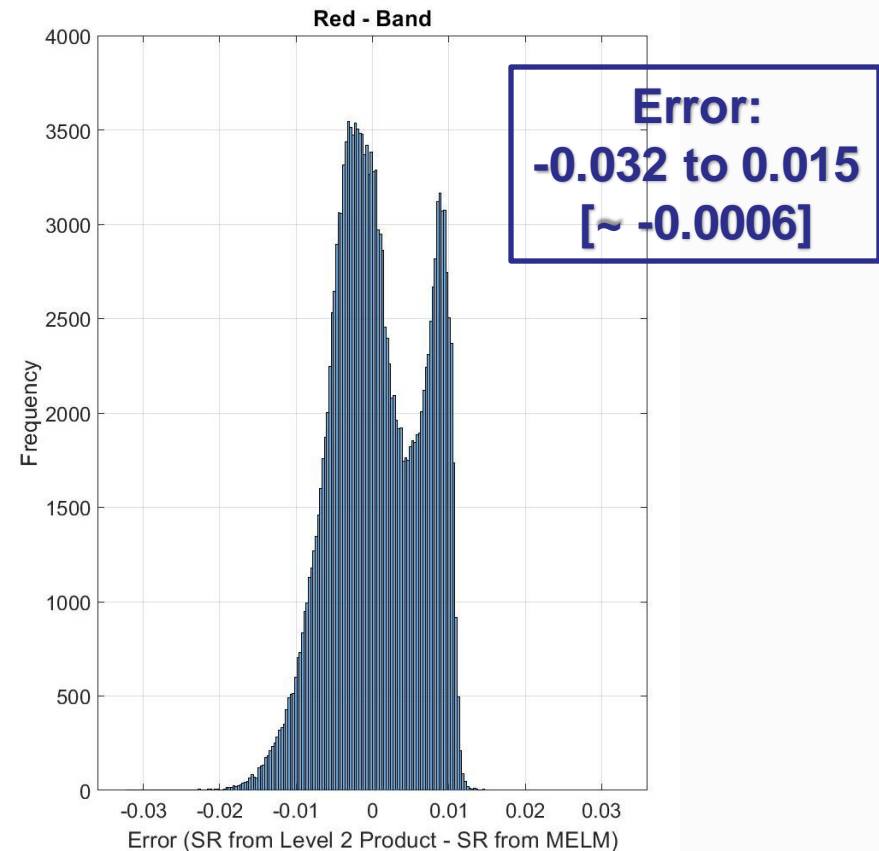
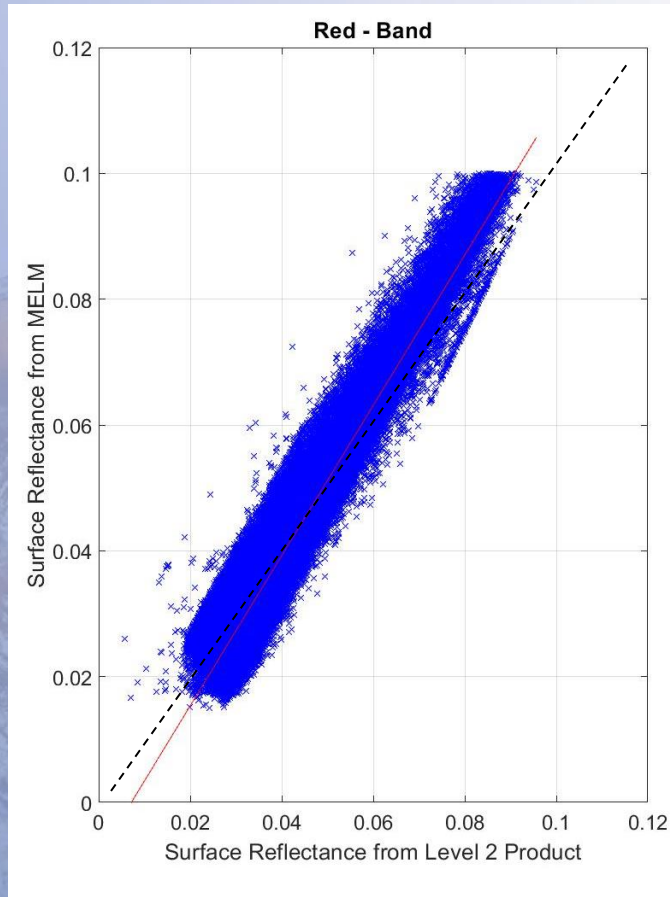


Mirror-based Empirical Line Method

Preliminary Results

Red Landsat-8

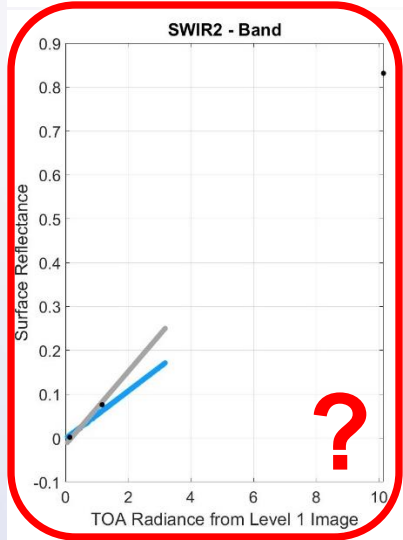
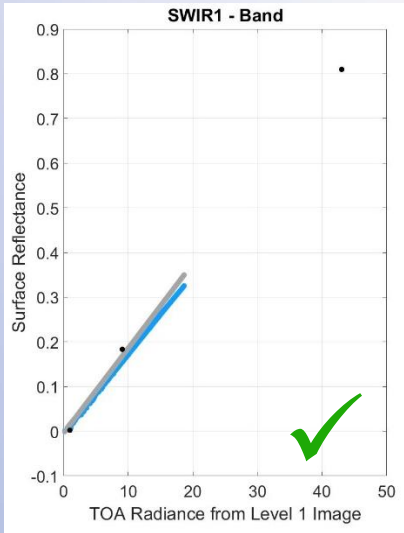
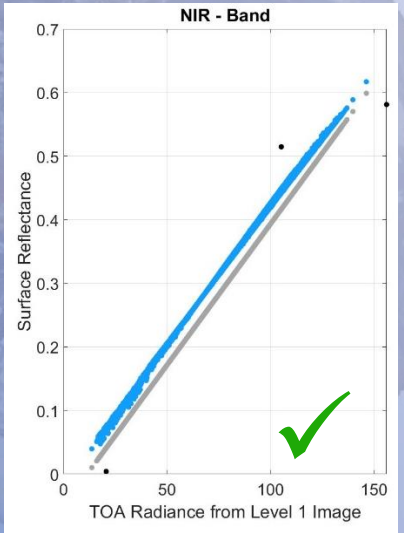
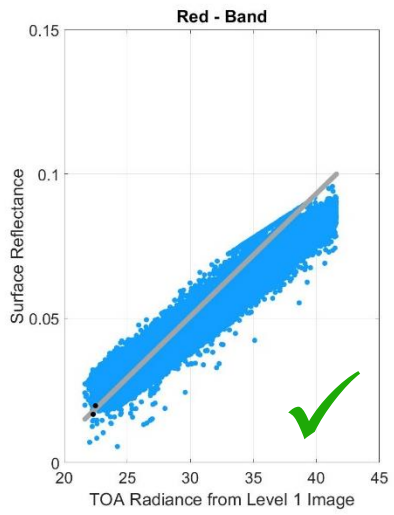
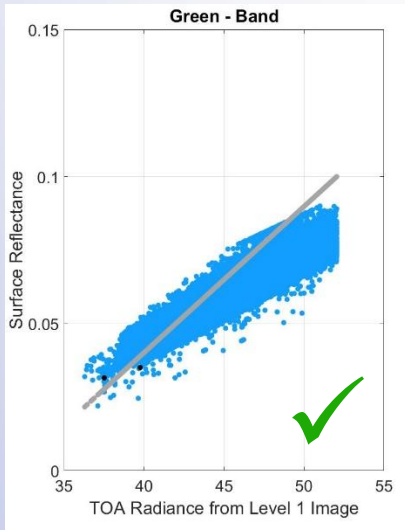
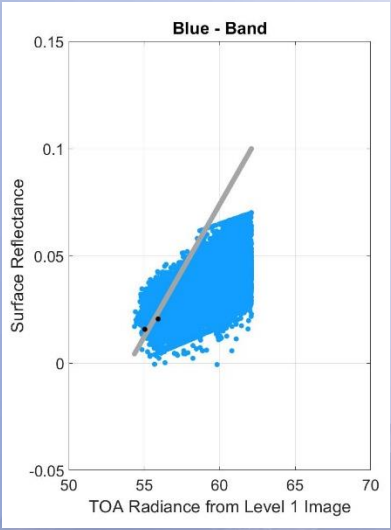
August 23, 2020



Mirror-based Empirical Line Method

Preliminary Results Landsat-8

August 23, 2020

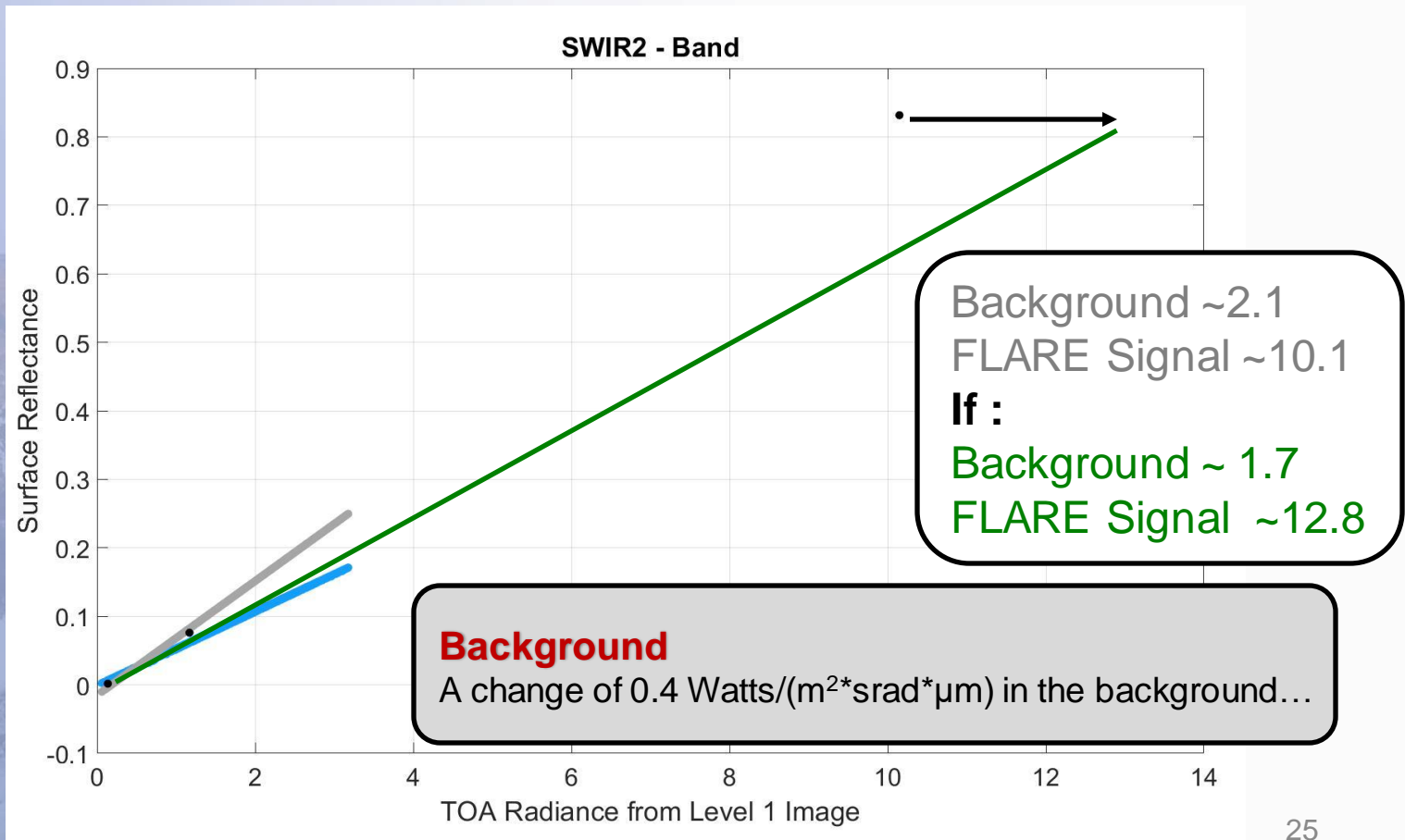


Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020

SWIR2 Landsat-8



Mirror-based Empirical Line Method

Preliminary Results

August 23, 2020



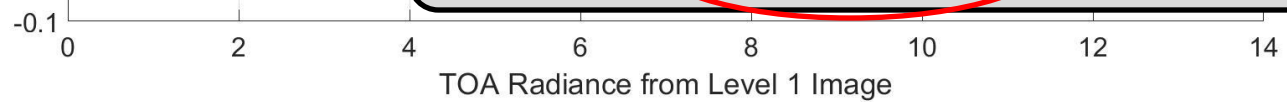
SWIR2 - Band

2.14 ± 0.26
[Watts/(m²*srad*μm)]

2-Sigma
 2.14 ± 0.52
[Watts/(m²*srad*μm)]

Background ~2.1
FLARE Signal ~10.1
Background ~ 1.7
FLARE Signal ~12.8

Background
A change of 0.4 Watts/(m²*srad*μm) in the background...



Mirror-based Empirical Line Method

Preliminary Results Landsat-8

Summary → August 23, 2020

Mean Error

$$ME = \frac{1}{n} \sum_{i=1}^n (Y_i - \hat{Y}_i)$$

Mean Absolute Error

$$MAE = \frac{1}{n} \sum_{i=1}^n |Y_i - \hat{Y}_i|$$

Band	ME	MAE
CA	-0.133	0.136
Blue	0.800 ± 0.018 (2.3%)	0.400 ± 0.018 (4.5%)
Green		
Red		
SWIR-1	-0.013	0.013
SWIR-2	-0.032	0.033
All Bands	-0.007	0.018

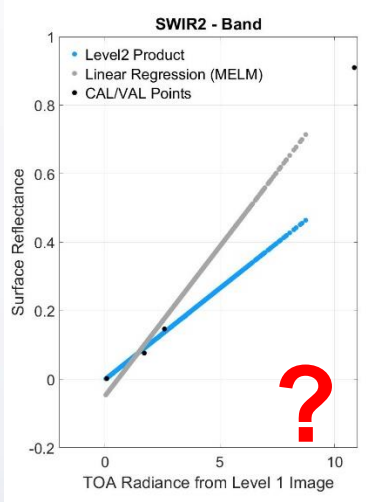
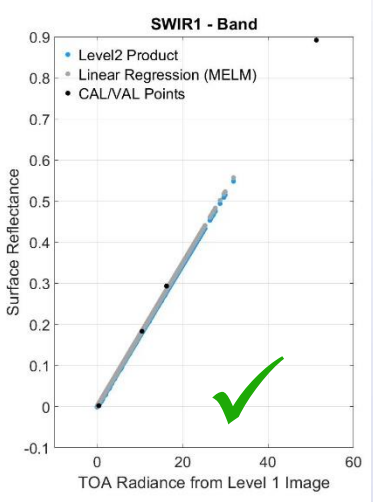
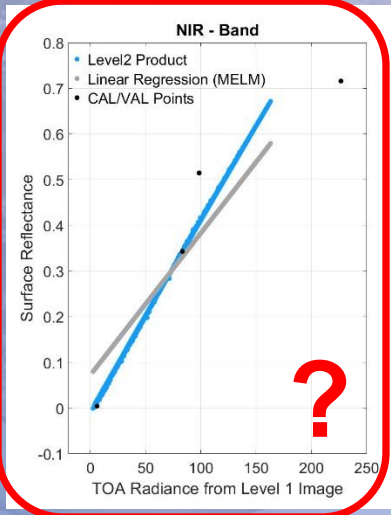
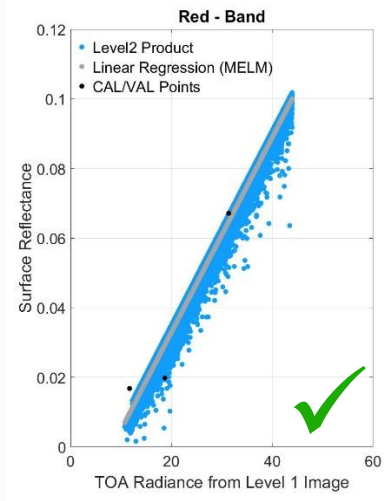
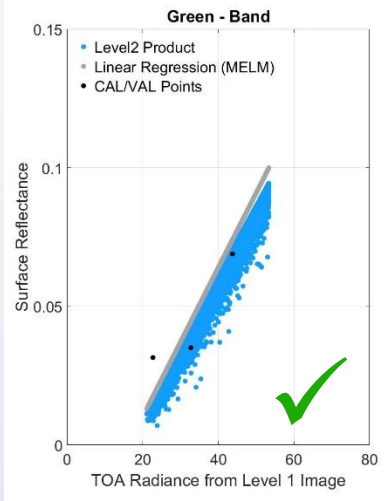
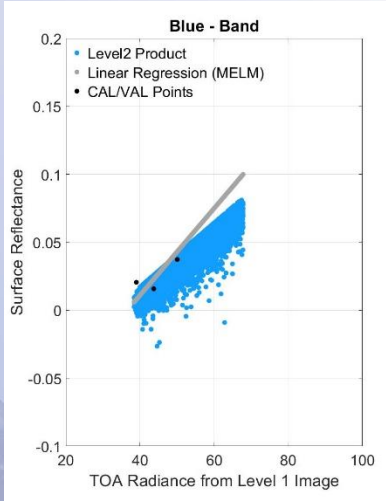
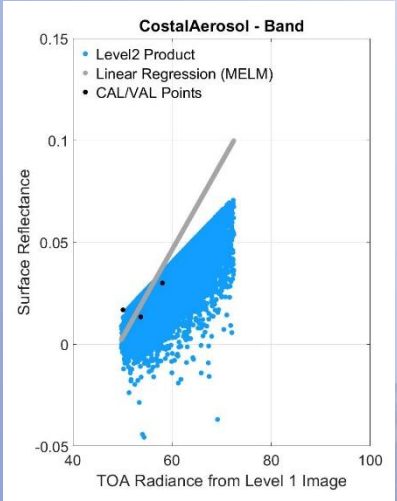
0.800 ± 0.018 (2.3%)
 0.400 ± 0.018 (4.5%)
 [reflectance units]

[except the CA]

*Error → (Surface Reflectance from Level 2 Product) - (Surface Reflectance from MELM)

Mirror-based Empirical Line Method

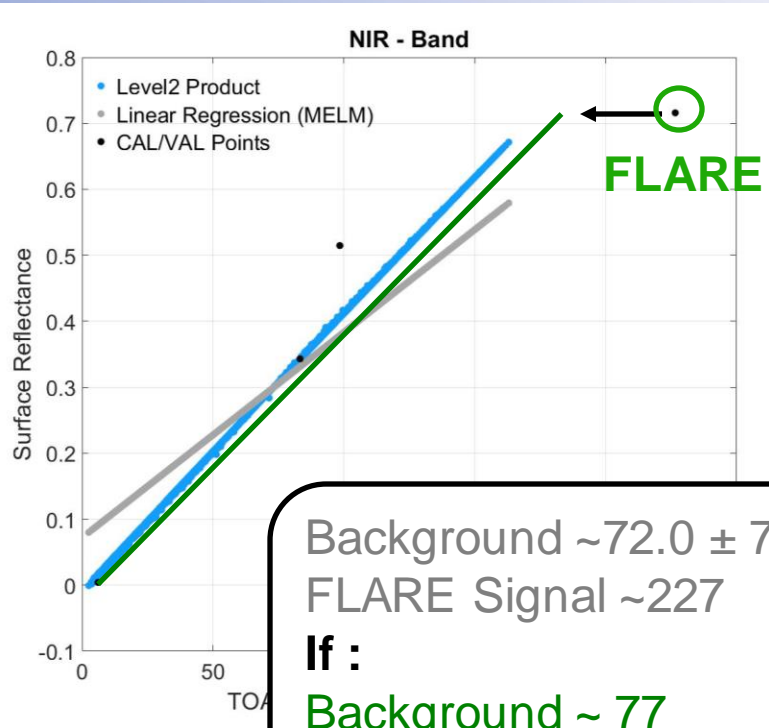
Preliminary Results Landsat-8 August 16, 2020



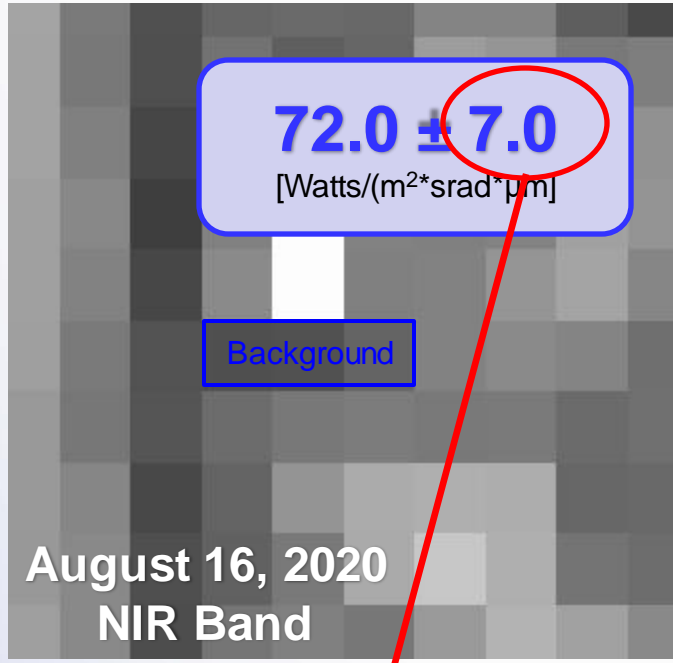
Mirror-based Empirical Line Method

Preliminary Results

Landsat-8



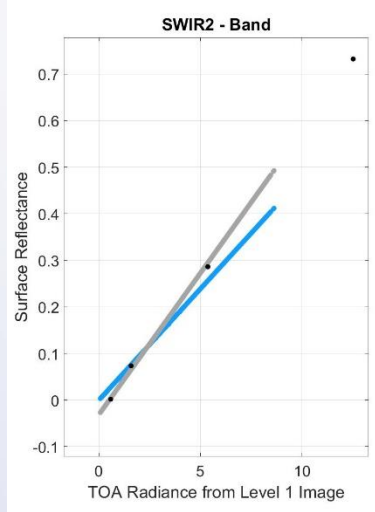
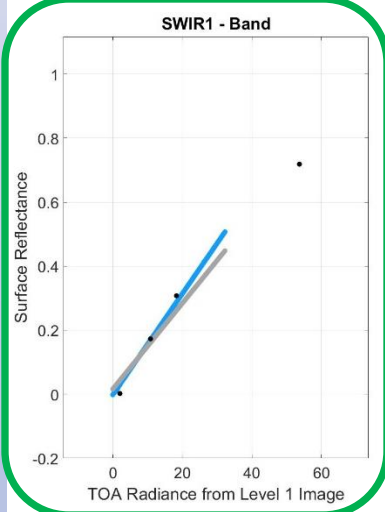
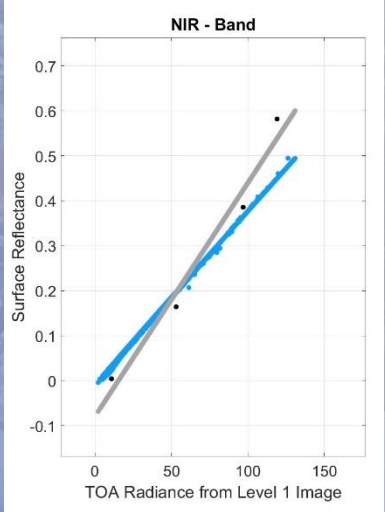
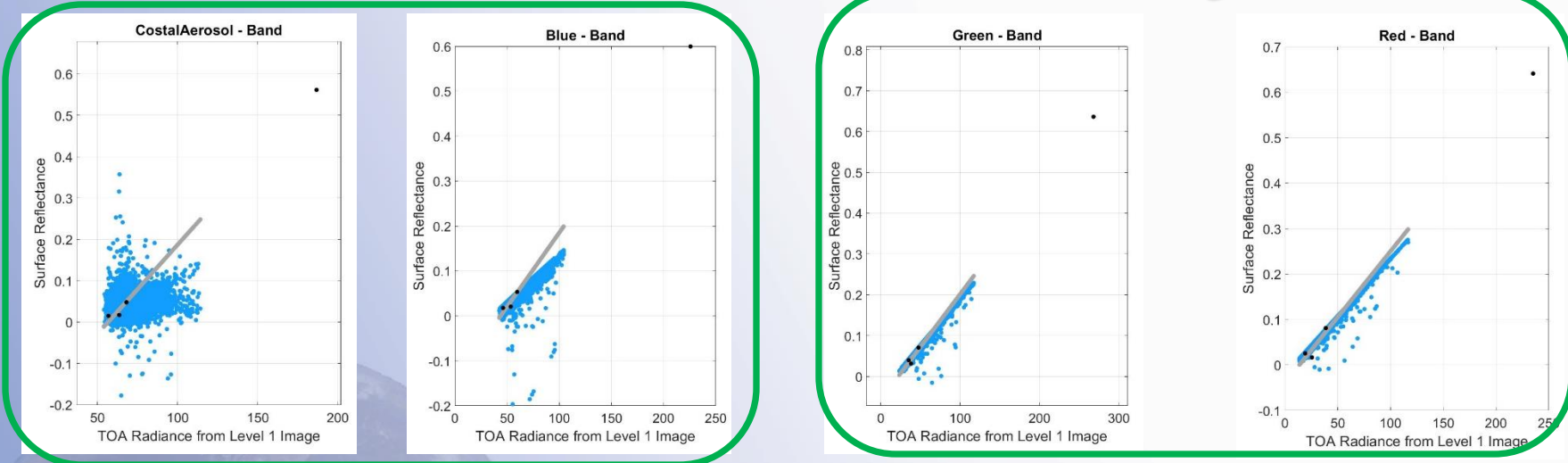
August 16, 2020



Background
A change of 5 Watts/(m²*srad*µm) in the background.

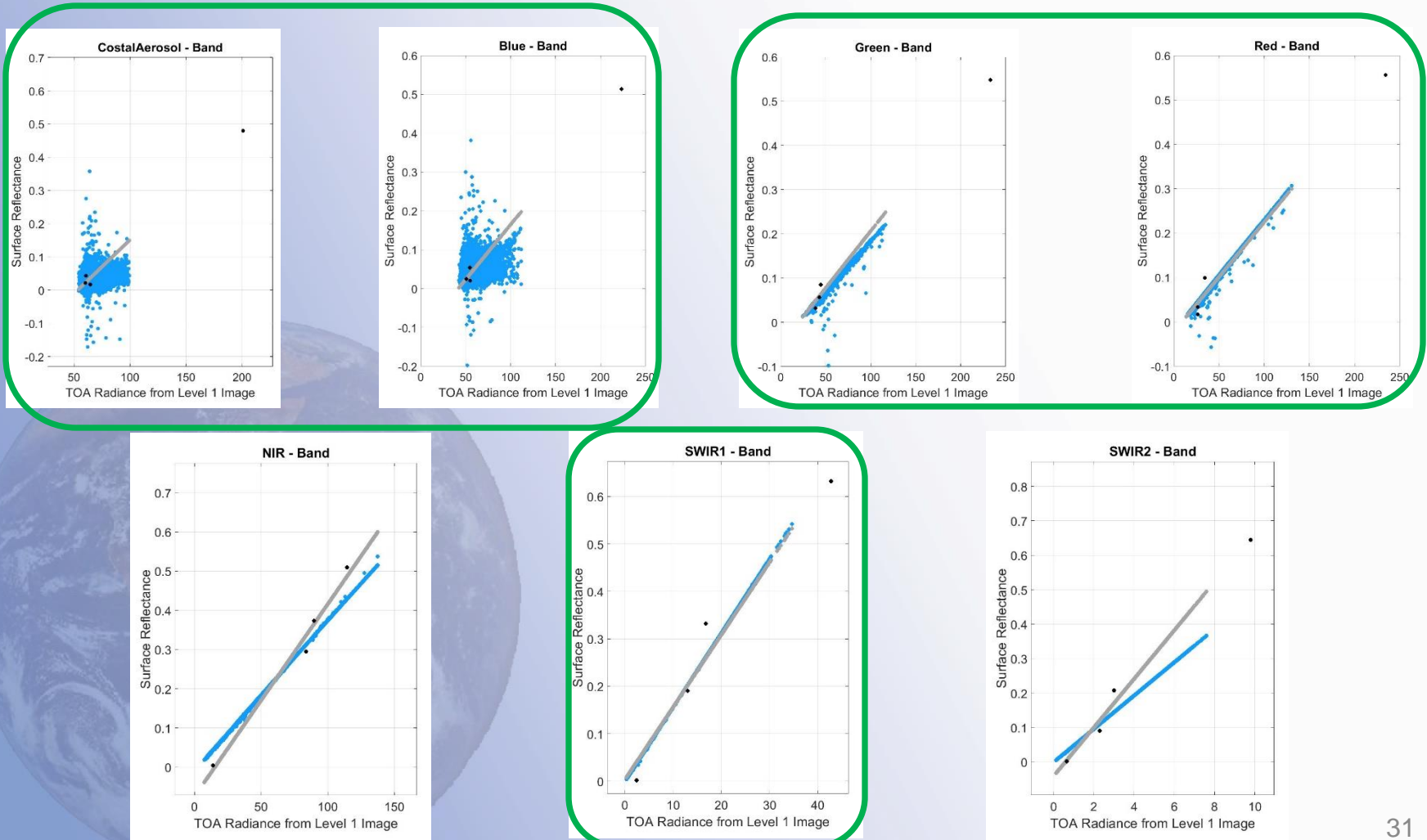
Mirror-based Empirical Line Method

Preliminary Results **Landsat-8** **May, 31 2021**



Mirror-based Empirical Line Method

Preliminary Results **Landsat-8** **June, 23 2021**



Mirror-based Empirical Line Method

Landsat-8

Summary

- ✓ In 2020 the vegetation around FLARE was removed and then replanted;
- ✓ The area around FLARE was more homogeneous in **2021** - consequently the background signal estimation is more accurate.

The average error considering all spectral bands has been reduced:

2020

MAE → ± 0.024

[reflectance units]

0.8 ± 0.024 → 3.0%

0.4 ± 0.024 → 6.0%

2021

MAE → ± 0.017

[reflectance units]

0.8 ± 0.017 → 2.1%

0.4 ± 0.017 → 4.3%

Mirror-based Empirical Line Method

Sentinel-2 → Bands 10m & 20 m

Sentinel-2 Bands	Central Wavelength (μm)	Resolution (m)
Band 1 - Coastal aerosol	0.443	60
Band 2 - Blue	0.490	10
Band 3 - Green	0.560	10
Band 4 - Red	0.665	10
Band 5 - Vegetation Red Edge	0.705	20
Band 6 - Vegetation Red Edge	0.740	20
Band 7 - Vegetation Red Edge	0.783	20
Band 8 - NIR	0.842	10
Band 8A - Vegetation Red Edge	0.865	20
Band 9 - Water vapour	0.945	60
Band 10 - SWIR - Cirrus	1.375	60
Band 11 - SWIR	1.610	20
Band 12 - SWIR	2.190	20

→ 9 pixels impacted by the FLARE system;

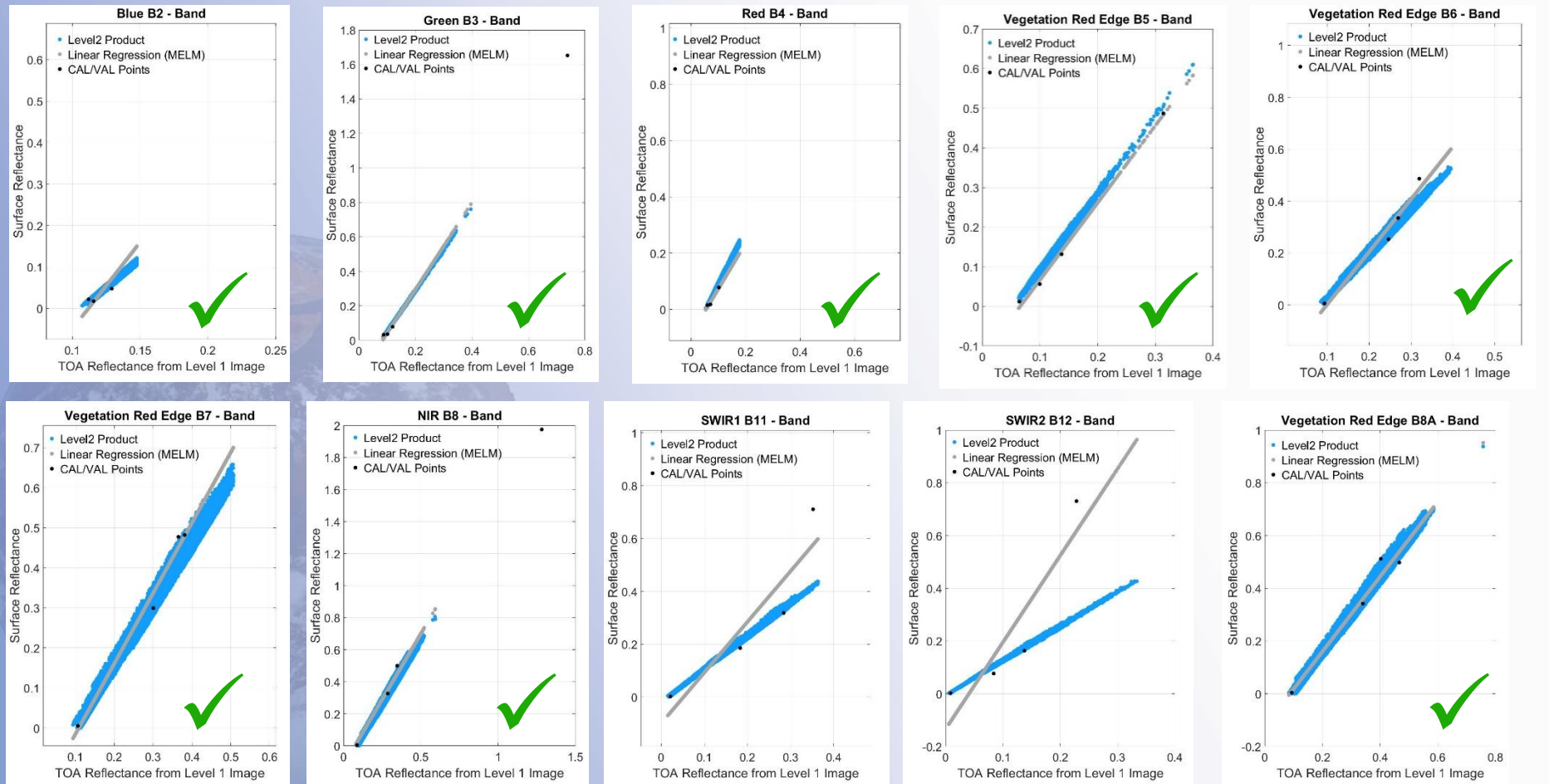
→ 4 pixels impacted by the FLARE system;

Mirror-based Empirical Line Method

Preliminary Results

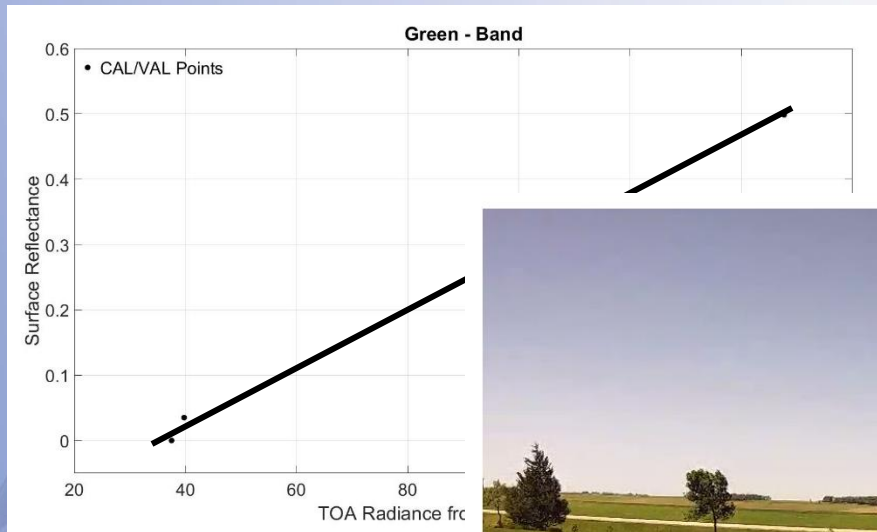
August 25, 2020

Spectral Bands - Sentinel



Future Work: Two Mirror Systems

Two mirror systems may eliminate the need to know the background value:
 [but it MUST be exactly the same background - which may be hard to achieve]



$$slope = \frac{\rho_{surface_diffuse_mirror2} - \rho_{surface_diffuse_mirror1}}{L_{Image2} - L_{Image1}}$$

$$= \frac{\rho_{surface_diffuse_mirror2} - \rho_{surface_diffuse_mirror1}}{\sum_{i=1}^n (r_i - r_{background})}$$



**2022
Lantern Flare**



slope

$$slope = \frac{\Delta_Y}{\sum_{i=1}^n (L_{n_mirror2}) - \sum_{i=1}^n (L_{n_mirror1})}$$

Future Work

Final Considerations

- ✓ The Mirror-based Empirical Line Method (FLARE system) has great potential for evaluating Level-2 products;
- ✓ Two key information for surface reflectance validation (Level-2):
 - (1) **Diffuse to Global Ratio** [Lambertian Equivalent Reflectance Factor]; and
 - (2) **Background Signal** [leave only the signal coming from the mirrors];
- ✓ Then Mean Absolute Error considering all spectral bands was **0.024** and **0.017** in 2020 and 2021, respectively.
- ✓ The area around FLARE is even more homogeneous in **2022** - consequently the background signal estimation is more accurate.

References

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- <https://flare-network.com/>

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Brandon Russell, Chris Durell, Larry Leigh

Thank you!

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