

BRIX-2: Second Biomass Retrieval Intercomparison eXercise

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What is BRIX-2?



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- BRIX-2 represents a CEOS WGCV task to intercompare algorithms specifically for biomass mapping using current and future spaceborne missions. It will be coordinated by ESA and NASA
- These objectives shall be achieved by making available **standardised test cases** (based on airborne campaign and spaceborne simulated data), inviting the scientific community to **develop and apply retrieval algorithms** based on this test case, and finally **compare and evaluate the performance** of submitted results.
- For the purpose of an objective algorithm evaluation, the exercise will be base on the ESA-NASA MAAP.

European Space Agency

The objectives of BRIX-2 are:



- 1. Provide an **objective**, **standardized comparison and assessment** of biomass retrieval algorithms developed for the **BIOMASS**, **NISAR and GEDI** missions, and fusion of these mission datasets.
- 2. Establish a forum to **involve scientists** in the development of retrievals that **have so far not been part of the biomass** community.
- 3. The adoption of vetted validation standards and methods to compare biomass estimates to reference datasets (e.g. field plots or airborne lidar biomass maps).
- 4. Collect inputs from the biomass user and scientific community on data formats and characteristics towards the generation of Analysis Ready Data.

Europe

What BRIX-2 is not!



- BRIX-2 should **not** be **a competition** where the best performing algorithm wins. The exercise should be a **scientific experiment** with a focus on the **intercomparison of algorithms** by validating derived biomass maps against in-situ reference measurements.
- BRIX-2 allows an increased understanding of **strengths** of the next generation of active remote sensing datasets, with a focus toward **algorithm fusion**. This is not intended as an algorithm competition, but **how we can combine lesson learned from the strengths of a range of algorithms**.

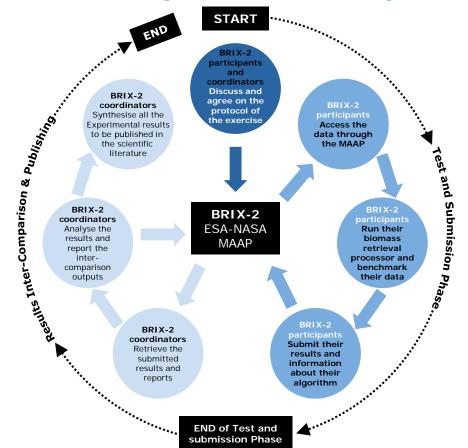


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Different steps and corresponding schedule





Milestones

- Experiment call (September 2020)
- Registration Deadline (November-December 2020 in Europe)
- First Workshop (end of January 2021)
- Results Submission Deadline (May 2021)
- Results Evaluation Report (September 2021)
- Second workshop (October-November 2021 in the US)





























Remote sensing and in-situ data

 Develop a biomass retrieval based on the data that has been acquired during the ESA-NASA AfriSAR campaign for the La Lopé, Mondah and Rabi super sites.

<u>Datasets from the MAAP that will be used:</u>

- P-band fully polarimetric interferometric SAR images and related additionnal information (incidence angles, DEM, etc.)
- **L-band** fully polarimetric interferometric SAR images and related additionnal information (incidence angles, DEM, etc.)
- ICESat-2 global photon counting lidar data, GEDI global data,
 LVIS L1-L4 data and derived biomass maps, discrete return lidar biomass maps and discrete return lidar DEM.
- The retrieval will be evaluated over the three sites with existing forest plot data and lidar estimates of biomass and forest height.



















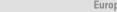












Evaluation of Results & Publication



- The evaluation will be done by ESA/NASA, following standards from the CEOS LPV protocol. This should guarantee a **fair evaluation**. ESA/NASA will release a **report to the participants summarising the evaluation results**.
- After the experiment has been closed we will make the evaluation scripts available on the MAAP. This allow people to repeat the experiment and compare their results against the published ones.
- ESA/NASA commit not to distribute the outcome of the exercise without prior consent of the participants.
- The results should easily be adapted for publication as a peer reviewed article co-authored by all participants who wish to publish the outcomes of the activity.



















Requirements for the MAAP



24 users (maximum) during 6 months (~8 users per mission).

→ All the required datasets and functionalities are already there!

















