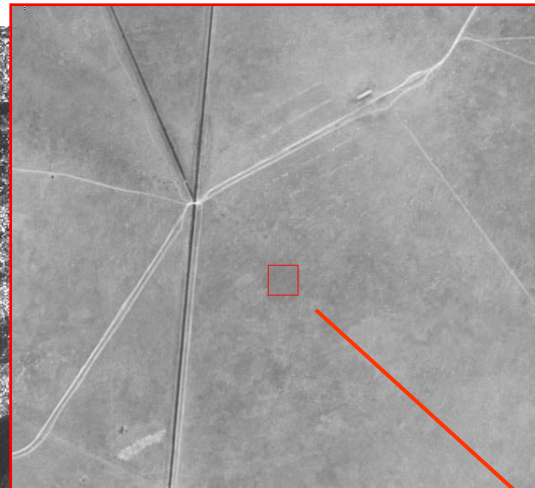




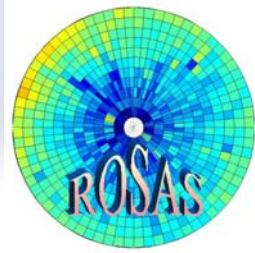
La Crau - ROSAS

(RObotic Station for Atmosphere and Surface)

P. Henry - A. Meygret



The calibration site

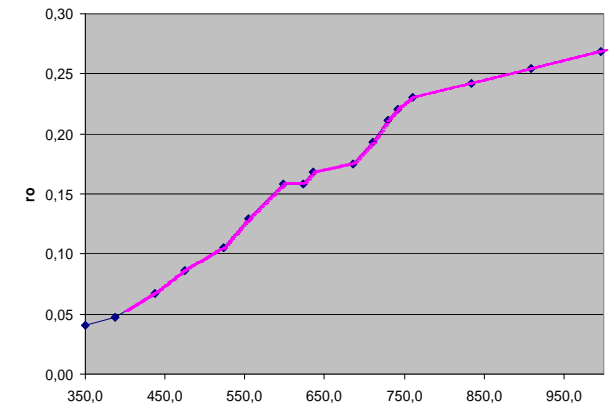


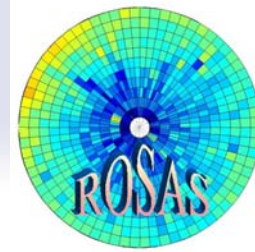
□ Situation: La Crau

- located South-East of France (lat. = 43.56° ; long. = 4.86°)
- rather good surface stability (dry area with small rocks)

□ Calibration historic

- first CNES campaign in march 1989 (coop. with LOA and INRA)
- 9 SPOT 1 calibrations (1989 \Rightarrow 1993)
- In 1994 : decision to develop an automatic calibration station





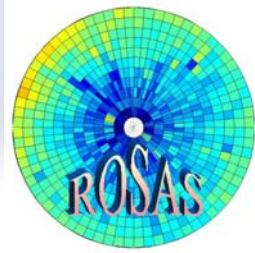
- CIMEL Instrument
(derived from AERONET one)



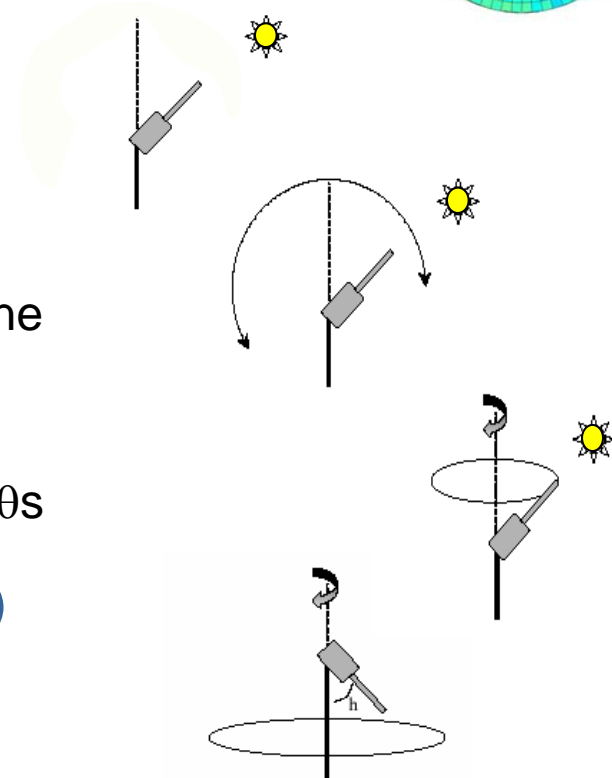
- Filters wheel : 8 filters + 1 dark plate
- 2 collimators and 2 detectors: Si and InGaAs

#	1	2	3	4	5	6	7	8	9	10	11	12	13
$\lambda(\text{nm})$	870Si	1600 InGaAs	670Si	1020 InGaAs	550Si		440Si		380Si	870InGaAs	1020Si		937Si

- Maintenance including calibration once a year



- ❑ « Sun » protocol
 - ❑ Direct sun view : extinction measurement
- ❑ « Principal plane » protocol
 - ❑ Sky radiance : measurements in the principal plane
- ❑ « Almucantar » protocol
 - ❑ Sky radiance : complete azimuth rotation for $\theta_v = \theta_s$
- ❑ « Ground » protocol (specific to this prototype)
 - ❑ Ground radiance measurements for different θ_v



- ⇒ Automatic and continuous acquisition :
first morning acquisition air mass < 5 - last evening acquisition air mass > 5
- ⇒ Complete measurement set every 90 min. : *SUN + ALM + PPL + GND (1st elevation) + SUN + GND (2nd elevation) + ... + GND (12th elevation) + SUN*
- ⇒ Transmitted to CNES every evening via a GSM link



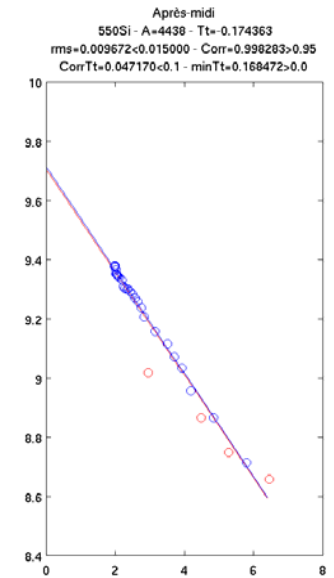
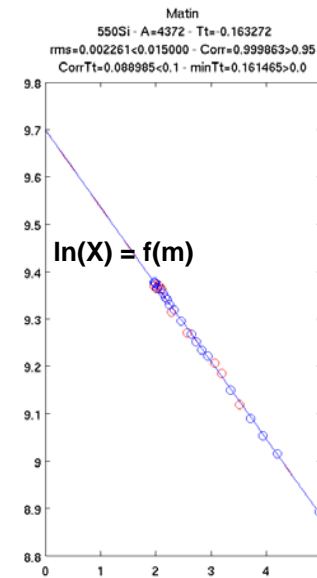
□ Irradiance calibration

- based on the Bouguer-Langley extinction law (all wavelength)

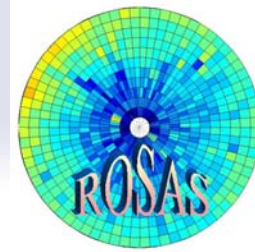
$$X_k = A_k * G_{uk} * I_k$$

(direct sun viewing)

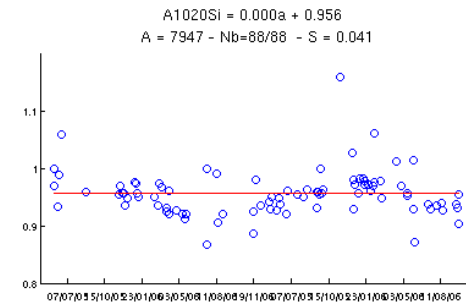
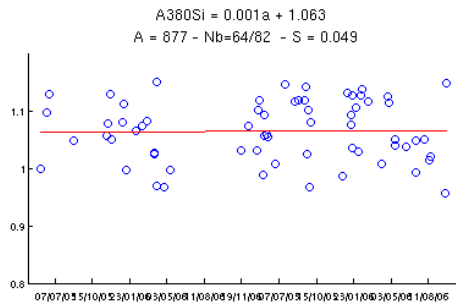
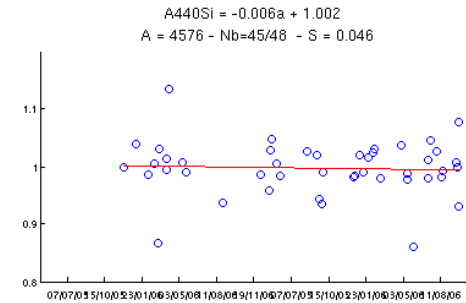
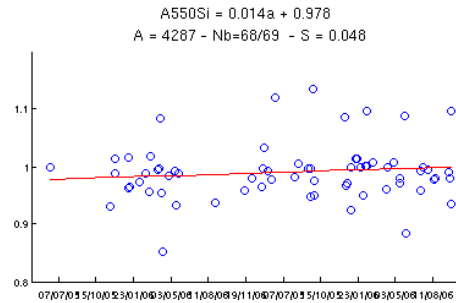
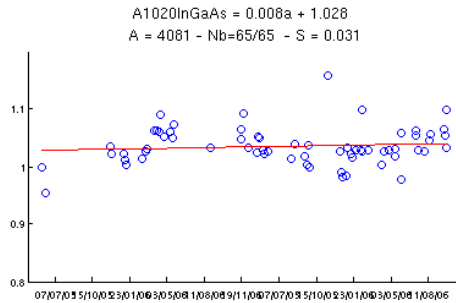
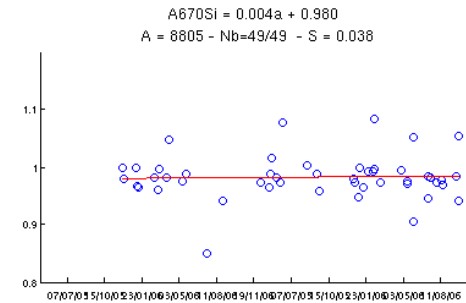
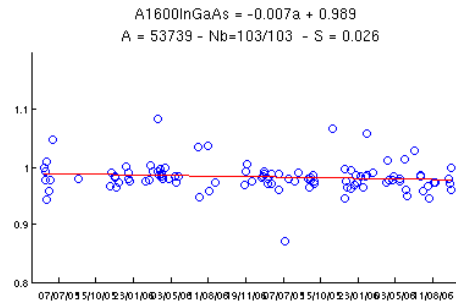
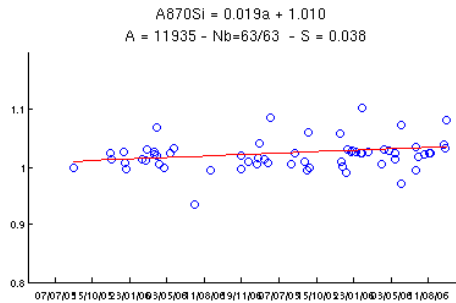
$$I_k = I_{0k} * (d/d_0) * \exp(-m * \tau_k)$$



A_k = instrument irradiance calibration coefficient



□ Irradiance calibration performed every day : A_k monitoring





□ Radiance calibration

- based on Rayleigh scattering for 380, 440, 550 nm bands

$$X_k = B_k * G_{kk} * L_k$$

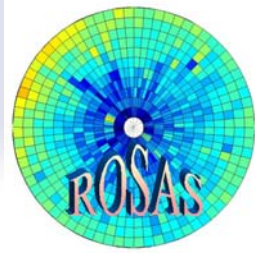
(sky radiance in the principal plan)

L_k estimated using a radiative transfert code

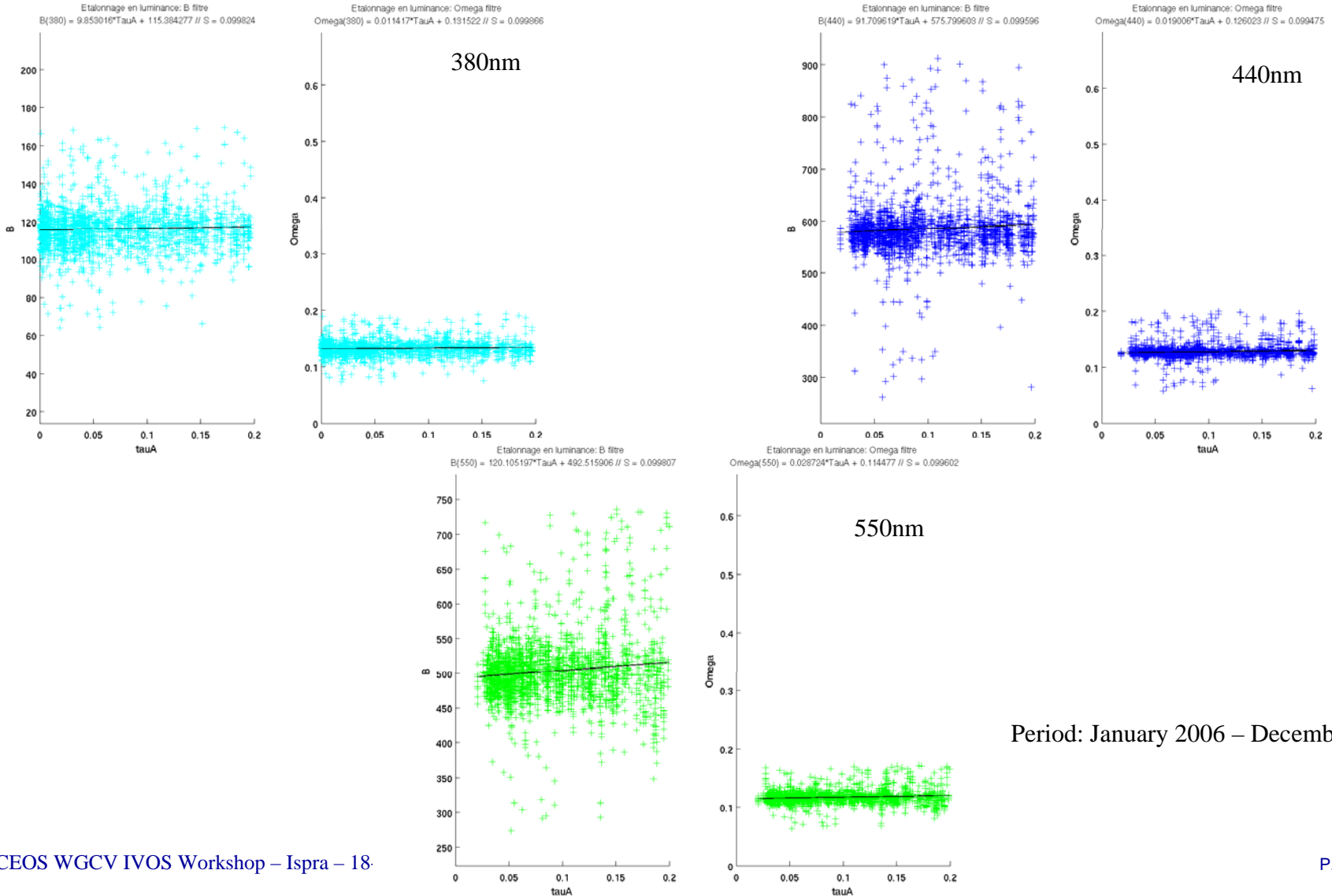
B_k = instrument radiance calibration coefficient

- $\Omega = B_k / A_k$: instrument solid angle (wavelength independent)

⇒ Computation of the radiance calibration coefficient for the other spectral bands (red, NIR and SWIR)

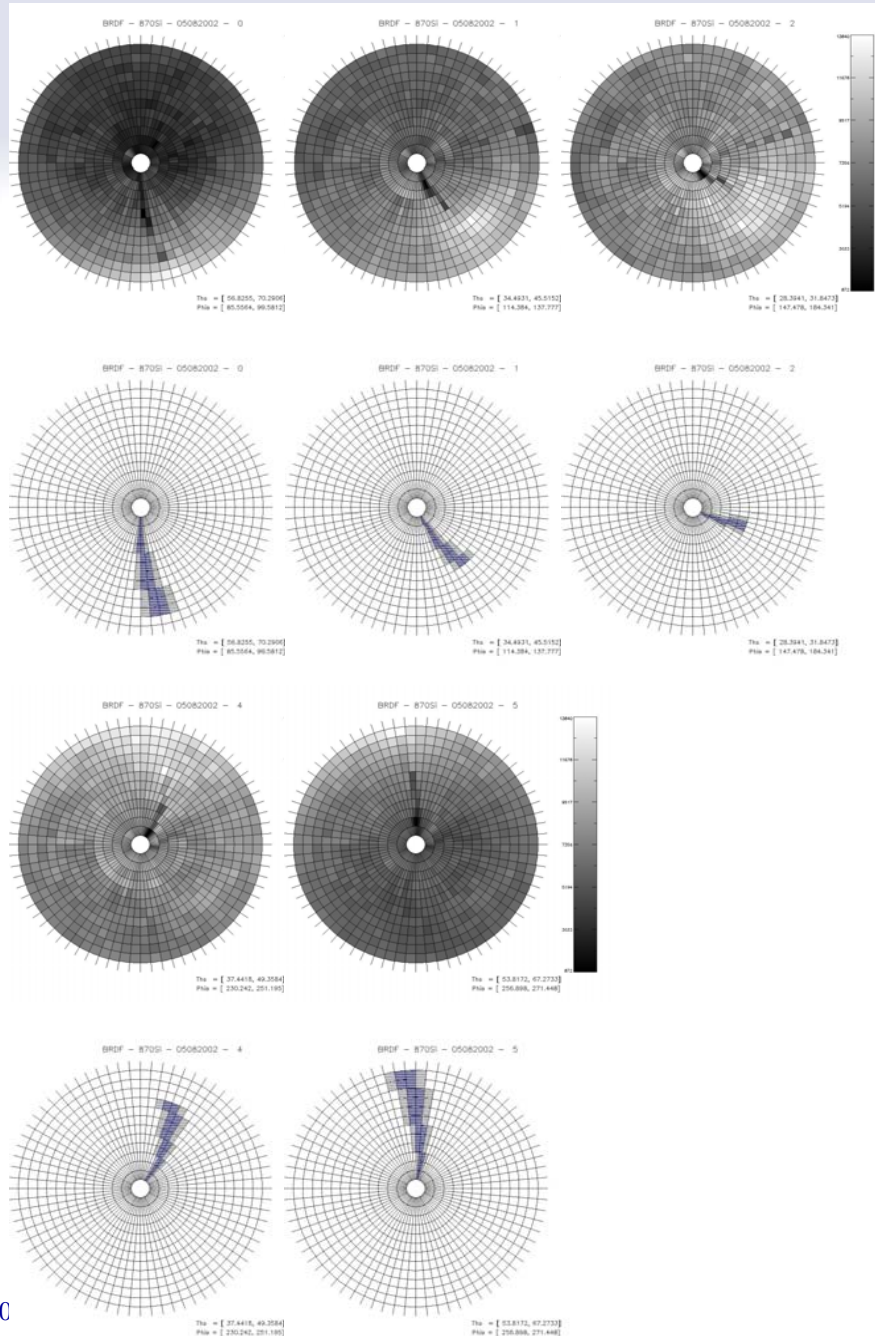
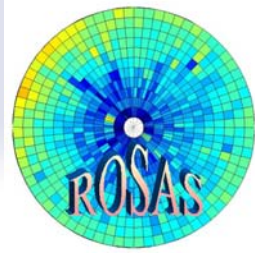


Rayleigh scattering calibration and Ω estimation



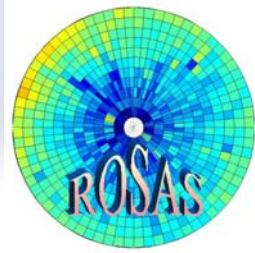
Period: January 2006 – December 2006

Ground reflectance

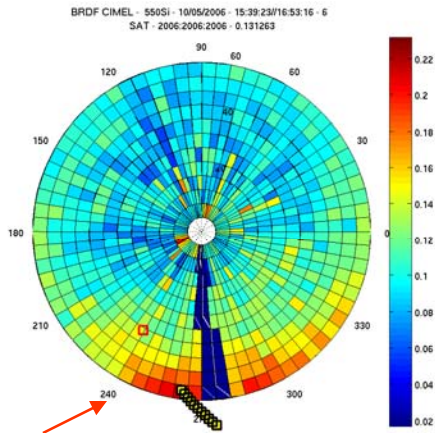


Shadow mask of the pole

Ground reflectance

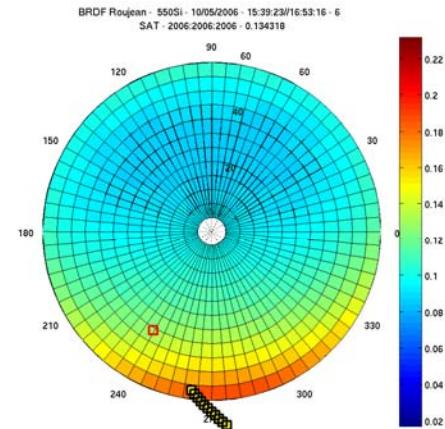


- Adjustment of a BRDF model (iterative filtering)

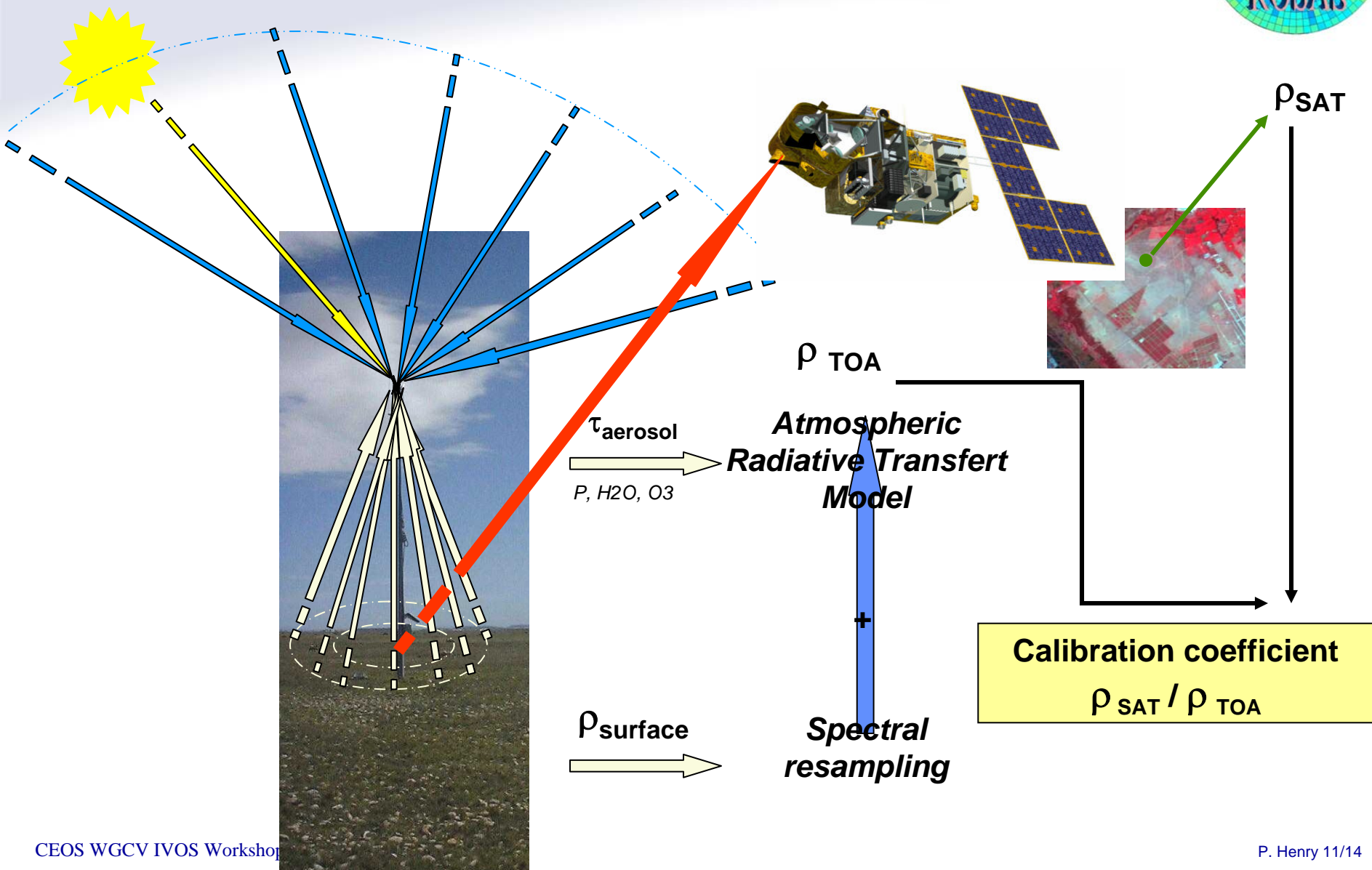
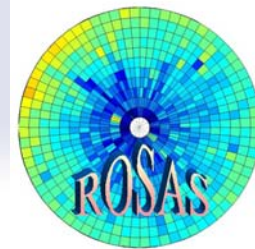


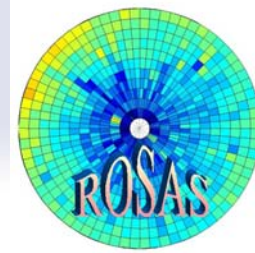
Hot spot

ROSAS ground reflectance (550nm)



Estimated BRDF model (550nm)

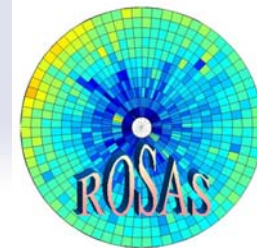




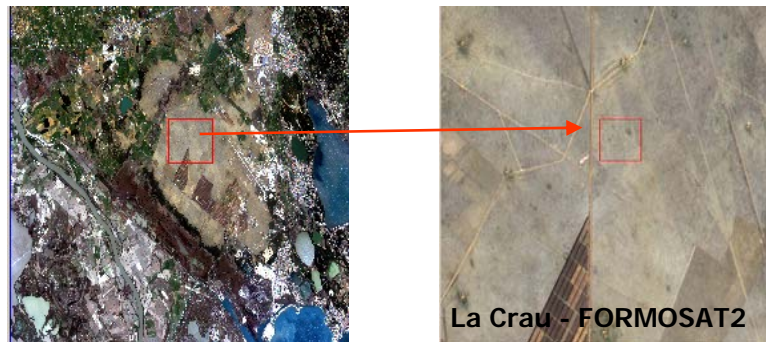
SPOT4 calibration

Date	B1 (green)	B2 (red)	B3 (NIR)
07-Nov-05	0.720	0.819	0.771
13-Mar-06	0.752	0.764	0.763
23-Mar-06	0.801	0.826	0.836
03-Apr-2006	0.770	0.824	0.786
02-Nov-06	0.732	0.822	0.794
13-Nov-06	0.751	0.842	0.796
22-Nov-06	0.729	0.807	0.789
Average	0.751	0.815	0.791
Standard deviation	0.026	0.023	0.022
Official cal. (01/06/06)	0.743	0.821	0.809
Discrepancy	+1.1%	-0.7%	-2.2%

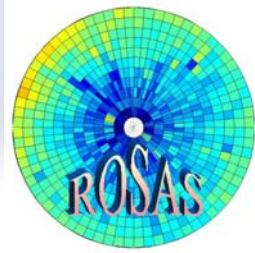
- 😊 **Low scattering over 7 measurements**
- 😊 **Good consistency with the official calibration**
- 😞 **No calibration for the SWIR band**



- ❑ ROSAS : operational for SPOT calibration
 - ❑ one calibration campaign per year
- ❑ Successfully tested with a set of Formosat 2 images



- ❑ Development of an operational software for ROSAS data archiving, testing and processing
 - ❑ industrial development
 - ❑ friendly interfaces, calibration results traceability, expertise toolbox
 - ❑ acceptance : October 2010



- ❑ Improve the calibration method :
 - ❑ H₂O content using the 937nm band
 - ❑ extend the calibration to the SWIR domain
- ❑ Transfer the ROSAS software to the operational calibration team
- ❑ Calibrate Pleiades using ROSAS during in-flight commissioning
- ❑ Try to install a 2nd ROSAS system on a new calibration site
- ❑ Study a ROSAS evolution for the Sentinel-2 in-flight calibration