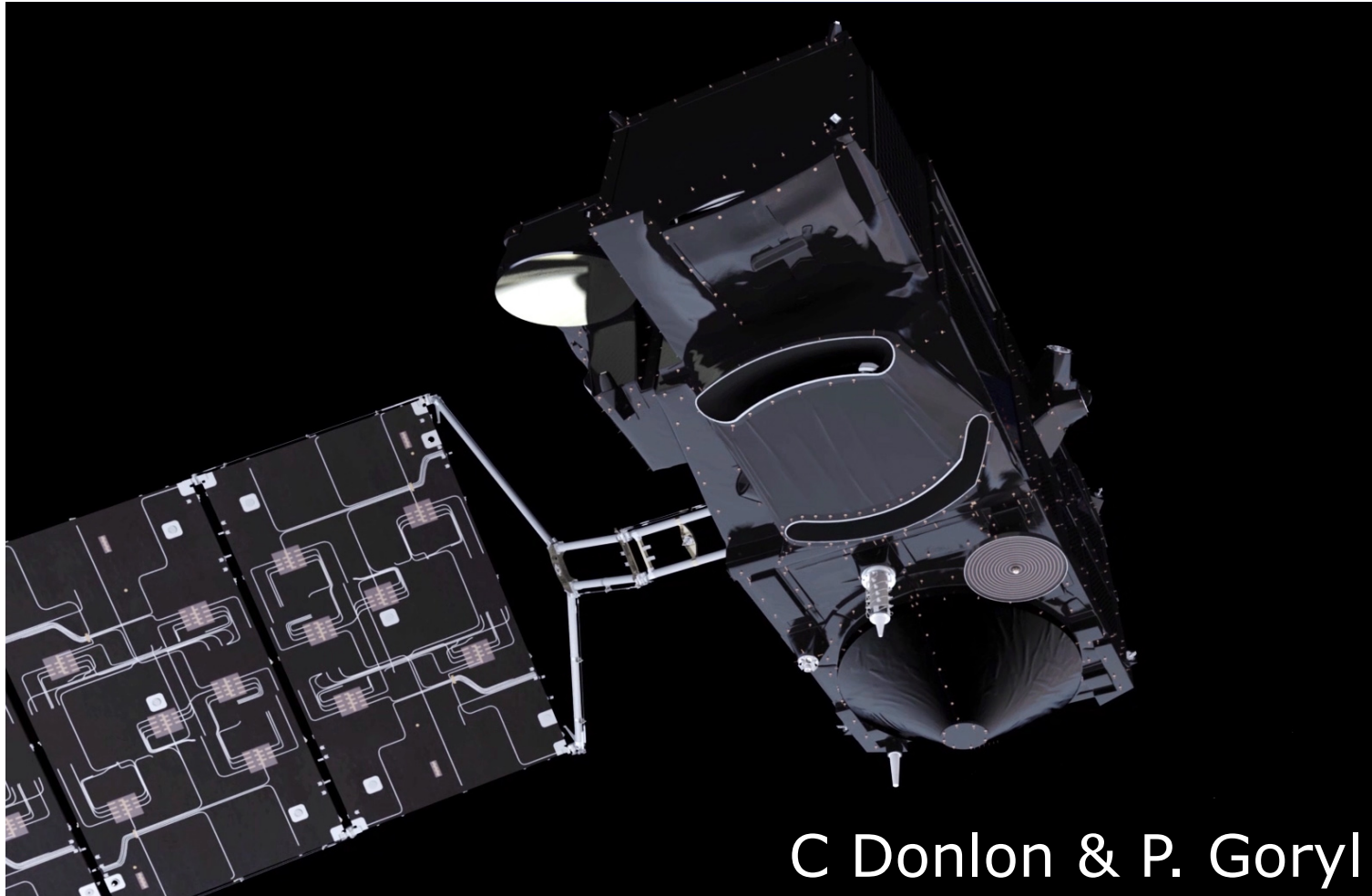


Fiducial Reference Measurements (FRM) for Sentinel-3



C Donlon & P. Goryl



Sentinel-3 Validation Team (S3VT), ESA/ESRIN, Italy, November 2013

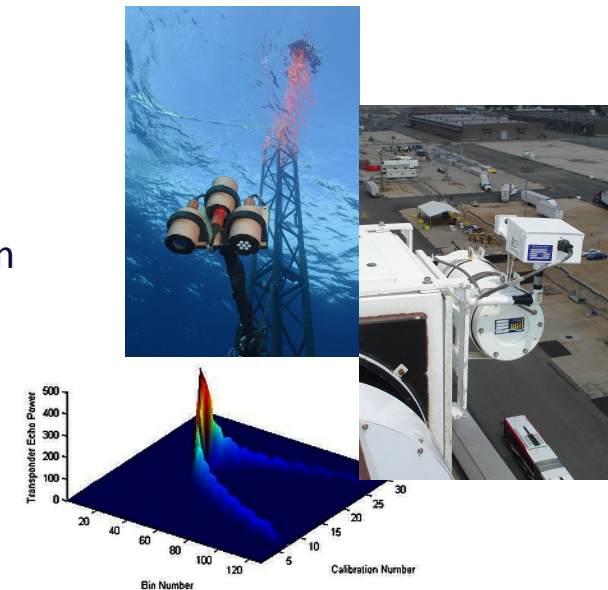


- What are Fiducial Reference Measurements (FRM)?
- Why do we need them at all?
- Examples of FRM in the context of Sentinel-3
- Summary
- Challenges for this meeting

Fiducial Reference Measurements (FRM)



- **fi·du·cial (adj)** *Regarded or employed as a standard of reference, as in surveying.*
 - [Late Latin fdcilis, from Latin fdcia, *trust*, from fdere, *to trust*; seebheidh- in Indo-European roots.]
- What's wrong with in situ?
 - It means everything to the uneducated
 - It's not tangible to a funding agency
 - It is not precise enough to argue for a validation program
- Sentinel-3 FRM are:
 - Linked to the S3 Cal/Val plan activities
 - Based on specific requirements
 - Forward thinking – long-term vision
 - Building on the existing capability
 - Have an inclusive approach: FRM are not Mission specific (e.g. S3A, B, C, D... S2A, B, C, D...all need ocean colour FRM..., All Altimeters need transponders for range calibration – and Sigma0...)

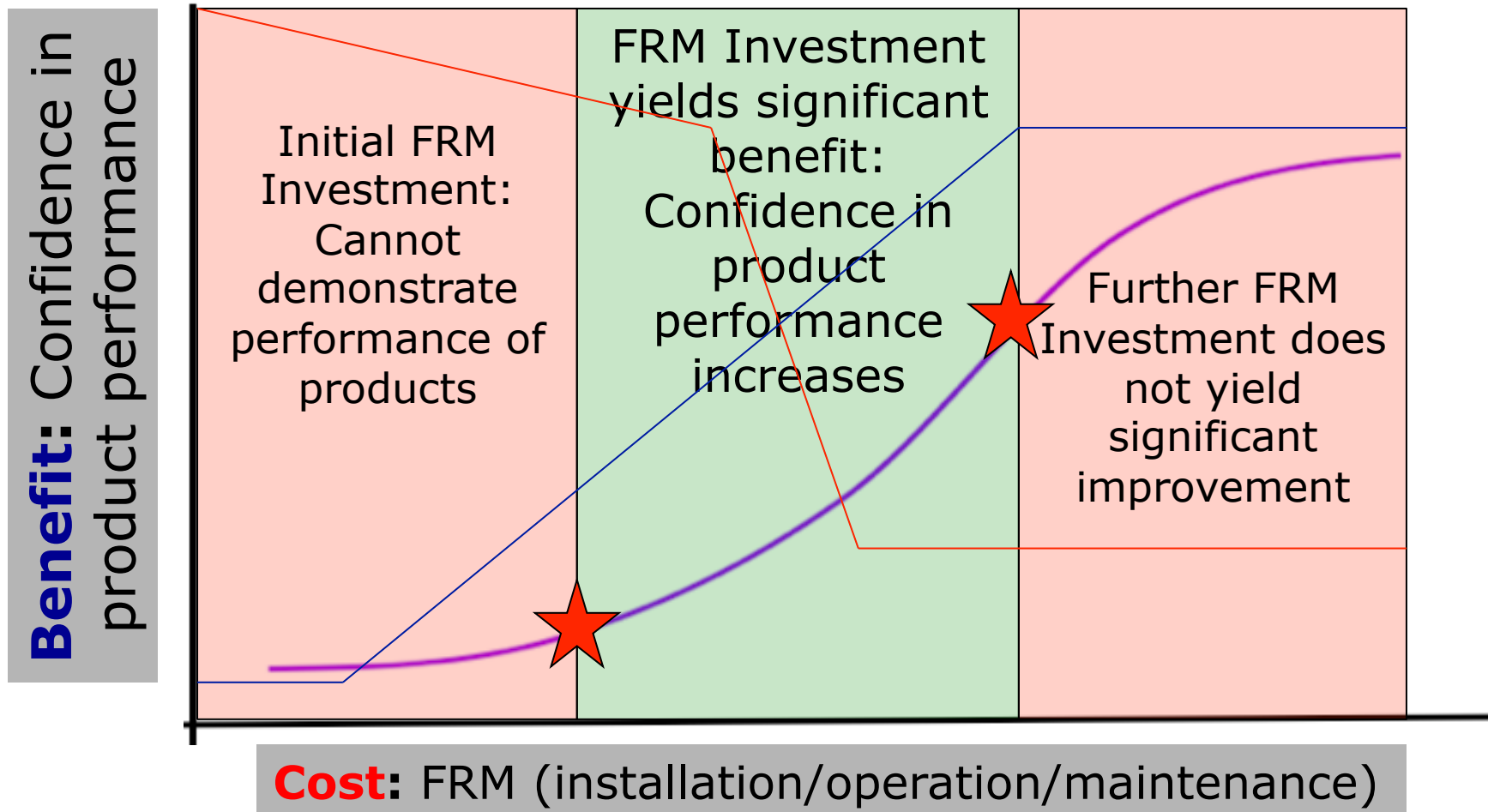


Why do we need FRM?



- FRM is the suite of ground measurements that provide the maximum Return On Investment (ROI) for the Mission by **delivering the required confidence in the data products for users.**
 - IF we have **no FRM** then we cannot really use the mission as we have no idea how accurate data products are
 - IF we have **many FRM** this is great scientifically (statistical significance, geographic coverage, robust network...) but incurs additional costs with reducing ROI
- **There is a balance between these two extremes to deliver a satellite mission with a KNOWN product quality that is “fit for Purpose”**

Is a mission product “fit for purpose”? It depends on our knowledge of how “good” it is...

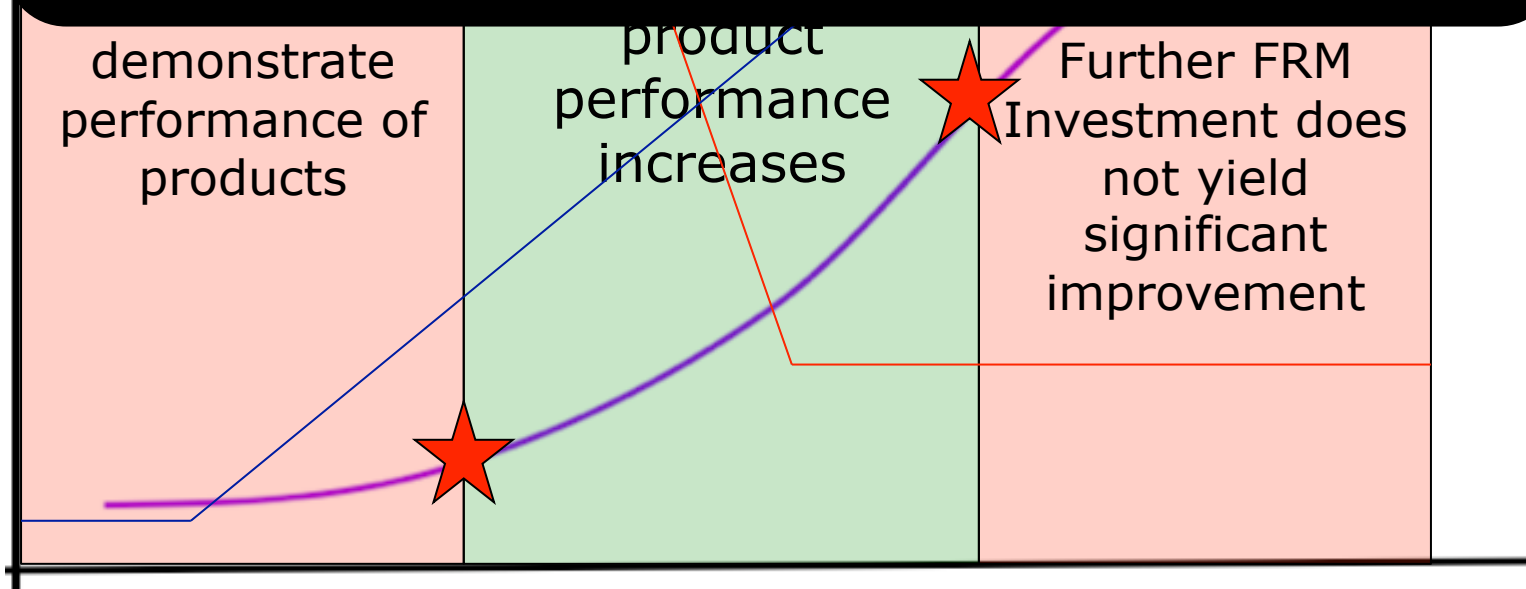


Is a mission product “fit for purpose”?
It depends on our knowledge of how “good” it is...



Q: What is the optimal FRM investment?
A: Sufficient to show that the Mission meets requirements:
A HIGH-IMPACT FRM

Benefit: Confidence in product performance



Cost: FRM (installation/operation/maintenance)



Example FRM: S3 SLSTR



- Ship-borne radiometers provide skin SST traceable to International standards.
- Drifting buoys provide wider geographical coverage and measure sub-surface SST (more complex validation) but not fully traceable.
- Moorings provide sub-surface SST – better temporal coverage but poor spatial coverage – may be partially traceable
- HR-ARGO floats: Provide vertical profiles moderate coverage but not fully traceable...



Example FRM: S3 SLSTR



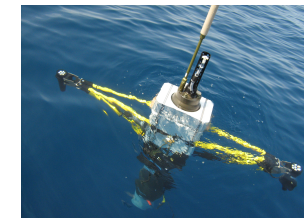
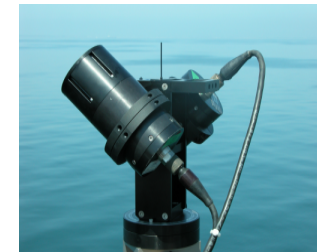
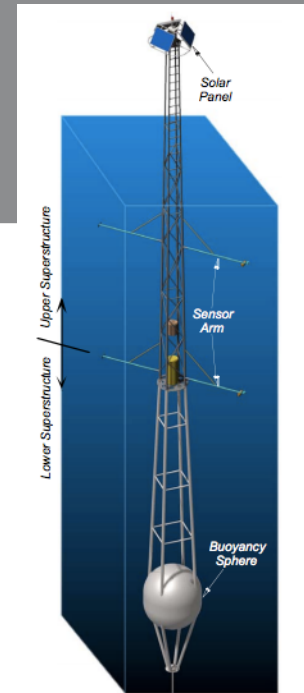
- Ship-borne radiometers provide skin SST traceable to International standards.
- Drifting buoys provide wider geographic coverage and measure sub-surface (more complex validation) but are partially traceable.
- Moorings provide surface SST – better temporal coverage but poor spatial coverage – partially traceable
- Underway floats: Provide vertical profiles – generate coverage but not fully traceable...

Which one is a high impact FRM?



Example FRM: S3 OLCI

- We need FRM to perform vicarious calibration of OLCI - Boussole, Moby, others (statistics needs at least 3 points to work with...) - other data – aerosols?
- We need FRM to perform regional algorithm development and validation
 - Ship data, moorings, AERONET-OC, Platforms...
- FRM should be capable of coping with sensor specific issues (e.g. geometry of OLCI vs other OC sensors...evolution of S3 OLCI A/B → C/D units? What about S2 MSI?)

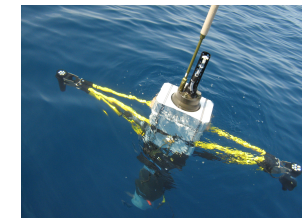
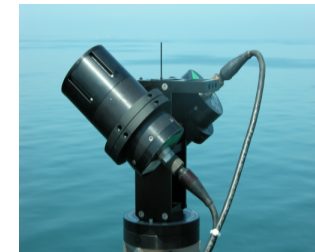
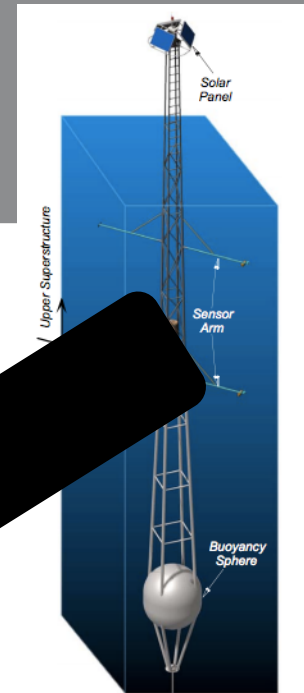


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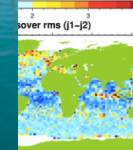
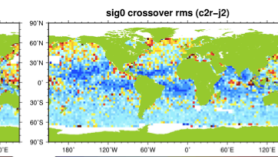
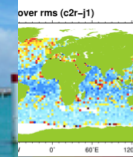
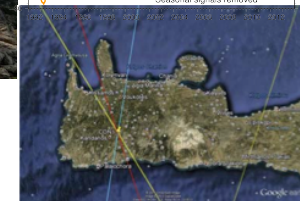
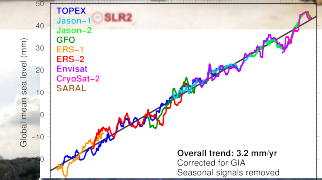
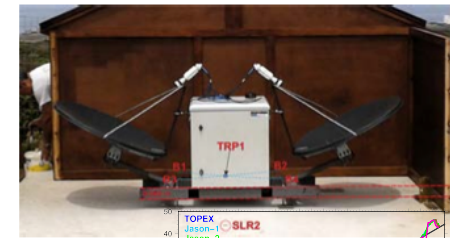
Which one is a high impact FRM?



Example FRM: S3 SRAL



- Deployment of Transponders (Range and Sigma-0)
- Comparison to Tide gauges (with GPS? Without GPS? Leveled?)
- Multi-Mission crossovers (Sigma0, wind, sea level?)
- Wave and wind model?
- New approaches?



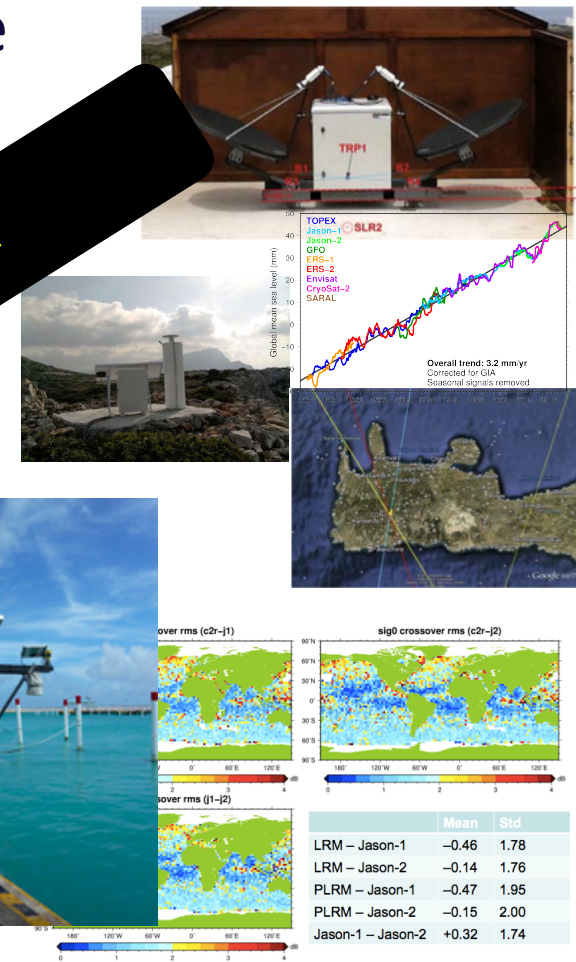
	Mean	Std
LRM – Jason-1	-0.46	1.78
LRM – Jason-2	-0.14	1.76
PLRM – Jason-1	-0.47	1.95
PLRM – Jason-2	-0.15	2.00
Jason-1 – Jason-2	+0.32	1.74

Example FRM: S3 SRAL



- Deployment of Transponders (Range and Sigma-0)
- Comparison to Tide gauges (with GPS? Without GPS? Levelled?)
- Multi-Mission crossover (Sigma0, wind, ...)
- Wave and ... model?
- New ... approaches?

Which one is a high impact FRM?



What makes an FRM and FRM?



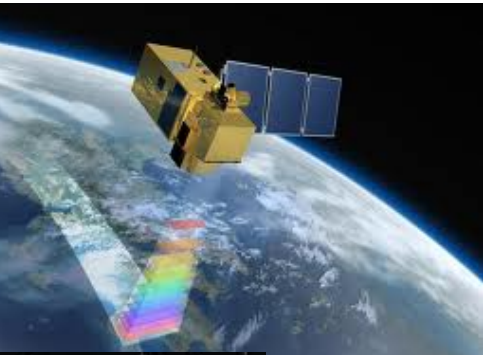
- Standards Traceability via round-robin inter-calibration of instruments?
- Independence?
- An Uncertainty budget?
- Published papers?
- Good management?
- Maintenance of infrastructure and calibration?
- A good site? (atmosphere, gradients...)
- A long time series?
- “Because this is what was done in the past”?
- Good protocols (measurement, processing, archive, documents...)?
- Availability (data sharing)?
- Provides evidence that we meet mission requirements?



Summary



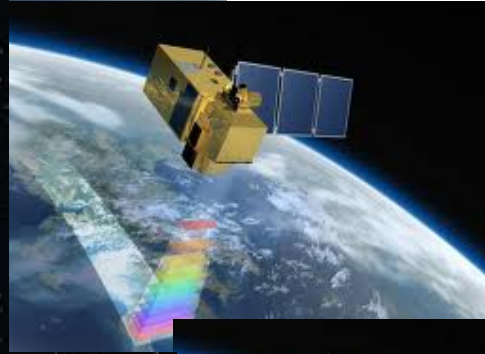
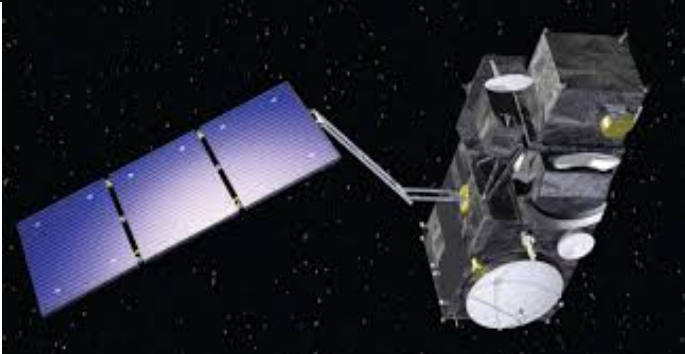
- The term “in situ” measurement brings fear to some eyes... costs are potentially enormous
- A refined process is required to move on from where we are – your S3VT sub-group chairs have a responsibility to “make it happen” – me included!
- A requirements-based (justified) and prioritized (cost-benefit) suite of measurements is obviously required to demonstrate that S3 products are “fit for purpose”
- The concept of Fiducial Reference Measurements (FRM) may be one way to develop a more palatable case in the long term
- Care is needed to define FRM appropriately
- Europe needs to build a secure FRM base of its own to provide the required confidence in EO measurements and fully realise the Return on Investment (ROI) for Sentinels



S2A



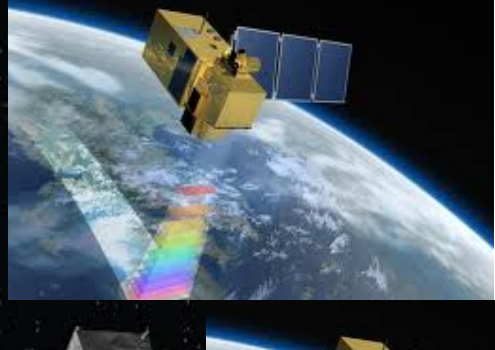
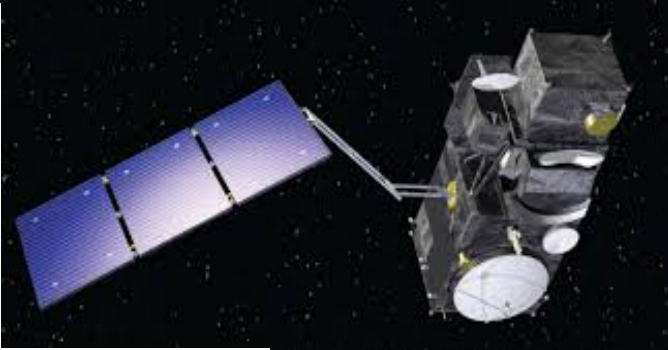
S3A



S2B

S3B

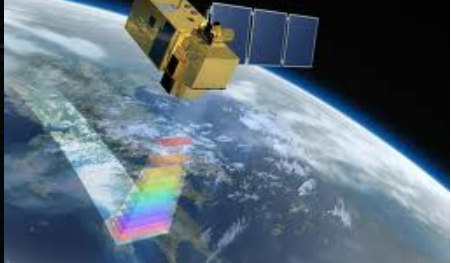
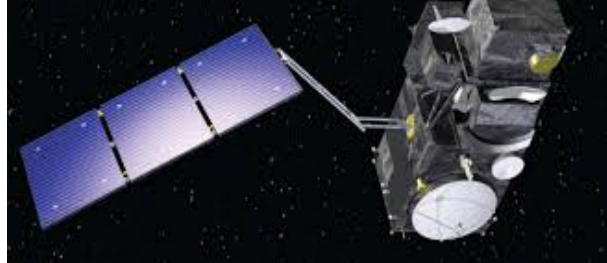
S3C

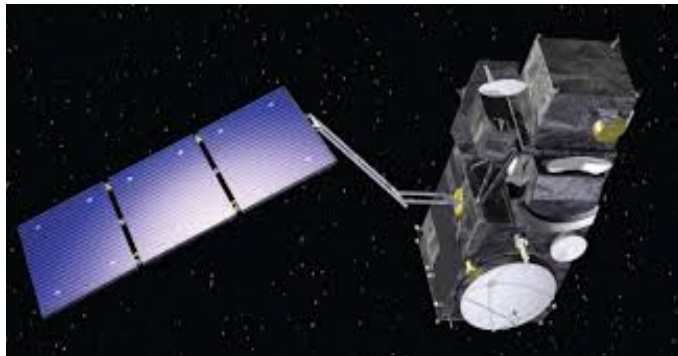


S2C&D

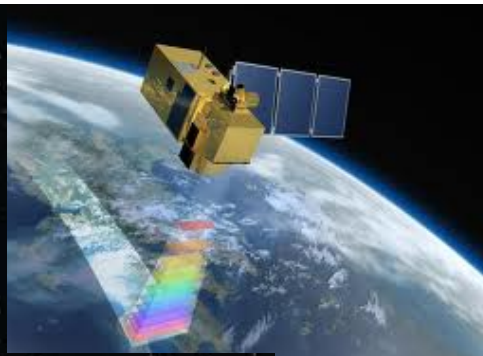
S3D

S3D





S3A



S2A



In Europe, we have a lot of Copernicus infrastructure in preparation – will we be able demonstrate its performance?

Can we demonstrate we have met requirements?

Are products “fit for purpose” within Copernicus?

S3D



Challenges for this meeting



- Only example FRM for S3 have been presented
What are the “actual” FRM?
- Can S3VT sub-groups define FRM?
- How should they be presented in the S3VT IP
and/or Cal/Val plan?
- What defines an FRM?
- Can we link requirements for FRM from the S3
Cal/Val plan?
- ...

- The *aim* of the first S3VT meeting is:
 - ***"to consolidate and document S3VT activities prior to launch to facilitate Phase E1 and Phase E2 cal/val planning"***
- **Output:**
 - A draft S3VT ***Implementation Plan (S3VT-IP)*** that will be the main reference of S3VT activities and planning for use by other entities within the Sentinel-3 Mission during Phase E1 and E2.

First S3VT meeting



- The *aim* of the meeting was to discuss the S3VT activities prior to the start of the implementation Phase E1
- **Output:**
 - A draft document that will be used to coordinate activities within the S3VT and ESRIN



S3VT activities
prior to the start of
Phase E1 and

the S3VT-IP
document

will be used to
coordinate activities
within the S3VT
and other entities
prior to the start of
Phase E1





Thank you - any
questions?

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